

Non-homogeneous linear systems

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where $\mathbf{A}(t) = [a_{ij}(t)]_{n \times n}$, $\mathbf{g}(t) = [g_1(t) \ \cdots \ g_n(t)]^T$ with $a_{ij}, g_i \in C(a, b)$ for all i, j .

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Theorem The general solution to the non-homogeneous DE

$$y'' + p(t)y' + q(t)y = g(t)$$

is given by $y(t) = y_p(t) + y_h(t)$

Undetermined coefficients

Consider 1st order non-homogeneous linear systems with *constant coefficients*

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- Write down the form of a particular solution \mathbf{x}_p .
- Find the coefficients (which are vectors) by substitution.

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Proof See appendix.

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In $\mathbf{x}_p(t) = (\mathbf{v}_{k+\ell} t^{k+\ell} + \cdots + \mathbf{v}_1 t + \mathbf{v}_0) e^{\alpha t}$, are the coefficients unique ?

Illustration Consider $\mathbf{x}'(t) = \mathbf{A}\mathbf{x}(t) + \mathbf{p}_k(t)e^{\alpha t}$

If α is an eigenvalue of \mathbf{A} with $A.M. = 3$ and $G.M. = 1$

associated to α one chain $(\mathbf{v}, \mathbf{u}, \mathbf{w})$ of generalized eigenvectors with length 3

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$\therefore \mathbf{v}_0, \mathbf{v}_1$ and \mathbf{v}_2 are not unique.

Example Solve the non-homogeneous system

$$\mathbf{x}'(t) = \begin{bmatrix} 4 & 2 \\ 3 & -1 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} -8t \\ 2t + 3 \end{bmatrix}$$

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Corresponding eigenvectors $\begin{bmatrix} 1 \\ -3 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$

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Complementary solution $\mathbf{x}_h(t) = c_1 \begin{bmatrix} 1 \\ -3 \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{5t}$

Example Solve the non-homogeneous system

$$\mathbf{x}'(t) = \begin{bmatrix} 4 & 2 \\ 3 & -1 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} -8t \\ 2t + 3 \end{bmatrix}$$

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Solve Eq. (1) and (3) $\mathbf{a} = \begin{bmatrix} \frac{2}{5} \\ \frac{16}{5} \end{bmatrix},$

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Example Find a particular solution to the system

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$$= \begin{bmatrix} (a_1t + b_1)e^{-2t} \\ (a_2t + b_2)e^{-2t} \end{bmatrix} \quad b_1, b_2 \text{ not unique}$$

Sub into sys

$$\left[a_1 e^{-2t} - 2a_1 t e^{-2t} - 2b_1 e^{-2t} \right]$$

Sub into sys

$$\begin{bmatrix} a_1 e^{-2t} - 2a_1 t e^{-2t} - 2b_1 e^{-2t} \\ a_2 e^{-2t} - 2a_2 t e^{-2t} - 2b_2 e^{-2t} \end{bmatrix}$$

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Compare coeff
$$\left\{ \begin{array}{l} -2a_1 = 4a_1 + 2a_2 \quad \text{1st entry, } t e^{-2t} \text{ term} \end{array} \right. \quad (1)$$

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Solve (1) and (3)
$$\mathbf{a} = \begin{bmatrix} \frac{-2}{7} \\ \frac{6}{7} \end{bmatrix},$$

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$$\mathbf{b} = \begin{bmatrix} b_1 \\ -3b_1 - \frac{1}{7} \end{bmatrix}$$
 Put $b_1 = 0$, say, obtain a particular soln

Exercise For each of the following case/sub-cases, write down the value of ℓ (*length of longest chain of generalized eigenvectors*).

	Value of ℓ
Case "simple"	
Subcase (2, 1)	
Subcase (2, 2)	
Subcase (3, 1)	
Subcase (3, 2)	
Subcase (3, 3)	

Variation of parameters

Consider the following non-homogeneous system

$$\mathbf{x}'(t) = \mathbf{A}(t)\mathbf{x}(t) + \mathbf{g}(t), \quad a < t < b$$

where $\mathbf{A}(t) = [a_{ij}(t)]$, $\mathbf{g}(t) = [g_1(t) \ \cdots \ g_n(t)]^T$, $a_{ij}, g_i \in C(a, b)$ for all i, j .

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- To find general solution to non-homogeneous system, try

$$\mathbf{x}(t) = \Phi(t)\mathbf{c}(t)$$

where $\mathbf{c}(t) = [c_1(t) \ \cdots \ c_n(t)]^T$, $c_i(t)$ to be determined

- **Product Rule** Suppose $\mathbf{F}(t) = [f_{ij}(t)]_{m \times n}$ and $\mathbf{G}(t) = [g_{ij}(t)]_{n \times p}$ where f_{ij}, g_{jk} differentiable. Then

$$\frac{d}{dt} \mathbf{F}(t) \mathbf{G}(t) =$$

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$$\mathbf{c}'(t) = \Phi(t)^{-1}\mathbf{g}(t) \quad \Phi(t) \text{ non-singular}$$

Put $\mathbf{x}(t) = \mathbf{\Phi}(t)\mathbf{c}(t)$ into system $\mathbf{x}'(t) = \mathbf{A}(t)\mathbf{x}(t) + \mathbf{g}(t)$

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$$\mathbf{\Phi}(t)\mathbf{c}'(t) = \mathbf{g}(t)$$

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General solution $\mathbf{x}(t) = \mathbf{\Phi}(t) \int \mathbf{\Phi}^{-1}(t)\mathbf{g}(t) dt$

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Example Solve the system $\mathbf{x}'(t) = \begin{bmatrix} -4 & 2 \\ 2 & -1 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} \frac{1}{t} \\ \frac{2}{t} + 4 \end{bmatrix}, \quad t > 0.$

Solution

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$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} c_1'(t) + \begin{bmatrix} -2 \\ 1 \end{bmatrix} (c_2'(t) e^{-5t} - 5c_2(t) e^{-5t})$$

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To find $c_1'(t)$ and $c_2'(t)$

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To find $c_1'(t)$ and $c_2'(t)$

- System of linear equation $\begin{cases} c_1'(t) - 2c_2'(t)e^{-5t} = \frac{1}{t} \end{cases}$

- Matrix equation

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} c_1'(t) + \begin{bmatrix} -2 \\ 1 \end{bmatrix} c_2'(t)e^{-5t} = \begin{bmatrix} \frac{1}{t} \\ \frac{2}{t} + 4 \end{bmatrix}$$

To find $c_1'(t)$ and $c_2'(t)$

- System of linear equation
$$\begin{cases} c_1'(t) - 2c_2'(t)e^{-5t} = \frac{1}{t} \\ 2c_1'(t) + c_2'(t)e^{-5t} = \frac{2}{t} + 4 \end{cases}$$

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 - Apply Cramer's Rule Det of coefficient matrix $\neq 0$
- Matrix equation

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} c'_1(t) + \begin{bmatrix} -2 \\ 1 \end{bmatrix} c'_2(t)e^{-5t} = \begin{bmatrix} \frac{1}{t} \\ \frac{2}{t} + 4 \end{bmatrix}$$

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- Matrix equation

$$\begin{bmatrix} 1 & -2e^{-5t} \\ 2 & e^{-5t} \end{bmatrix} \begin{bmatrix} c'_1(t) \\ c'_2(t) \end{bmatrix} = \begin{bmatrix} \frac{1}{t} \\ \frac{2}{t} + 4 \end{bmatrix}$$

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Therefore $c_1(t) = \ln t + \frac{8}{5}t + A, \quad t > 0$

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Therefore

$$c_1(t) = \ln t + \frac{8}{5}t + A, \quad t > 0$$

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General solution $\mathbf{x}(t) = \left(\ln t + \frac{8}{5}t + A \right) \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \left(\frac{4}{25}e^{5t} + B \right) \begin{bmatrix} -2 \\ 1 \end{bmatrix} e^{-5t}$

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$$= \left(\ln t + \frac{8}{5}t \right) \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \frac{4}{25} \begin{bmatrix} -2 \\ 1 \end{bmatrix} + A \begin{bmatrix} 1 \\ 2 \end{bmatrix} + B \begin{bmatrix} -2 \\ 1 \end{bmatrix} e^{-5t}$$

Variation of Parameters for n -th order DE

Illustration $n = 3$

$$y''' + p(t)y'' + q(t)y' + r(t)y = g(t) \quad (*)$$

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- Suppose y_1, y_2, y_3 are indep solns to associated homog DE.

To find a particular solution or general solution to (*), try

$$y = c_1(t)y_1(t) + c_2(t)y_2(t) + c_3(t)y_3(t)$$

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Impose **two conditions** on $c_1'(t), c_2'(t), c_3'(t)$

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Sub into (*), get **one more equation** for $c_1'(t), c_2'(t), c_3'(t)$

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Variation of Parameters for n -th order DE

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Impose **two conditions** on $c_1'(t), c_2'(t), c_3'(t)$

Sub into (*), get **one more equation** for $c_1'(t), c_2'(t), c_3'(t)$

- Transform to system, use $x_1 = y, x_2 = y', x_3 = y''$

$$\left\{ \begin{array}{l} x_1' = x_2 \\ \end{array} \right.$$

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- Suppose y_1, y_2, y_3 are indep solns to associated homog DE.

To find a particular solution or general solution to (*), try

$$y = c_1(t)y_1(t) + c_2(t)y_2(t) + c_3(t)y_3(t)$$

Impose **two conditions** on $c_1'(t), c_2'(t), c_3'(t)$

Sub into (*), get **one more equation** for $c_1'(t), c_2'(t), c_3'(t)$

- Transform to system, use $x_1 = y, x_2 = y', x_3 = y''$

$$\begin{cases} x_1' = x_2 \\ x_2' = x_3 \end{cases}$$

Variation of Parameters for n -th order DE

Illustration $n = 3$

$$y''' + p(t)y'' + q(t)y' + r(t)y = g(t) \quad (*)$$

- Suppose y_1, y_2, y_3 are indep solns to associated homog DE.

To find a particular solution or general solution to (*), try

$$y = c_1(t)y_1(t) + c_2(t)y_2(t) + c_3(t)y_3(t)$$

Impose **two conditions** on $c_1'(t), c_2'(t), c_3'(t)$

Sub into (*), get **one more equation** for $c_1'(t), c_2'(t), c_3'(t)$

- Transform to system, use $x_1 = y, x_2 = y', x_3 = y''$

$$\begin{cases} x_1' &= x_2 \\ x_2' &= x_3 \\ x_3' &= -r(t)x_1 - q(t)x_2 - p(t)x_3 + g(t) \end{cases}$$

That is

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -r(t) & -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix} \quad (**)$$

That is

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -r(t) & -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix} \quad (**)$$

Each solution y_i to (*) gives a solution $\begin{bmatrix} y_i \\ y'_i \\ y''_i \end{bmatrix}$ to system (**)

That is

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -r(t) & -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix} \quad (**)$$

Each solution y_i to (*) gives a solution $\begin{bmatrix} y_i \\ y'_i \\ y''_i \end{bmatrix}$ to system (**)

Fundamental matrix $\Phi(t) = \begin{bmatrix} y_1(t) & y_2(t) & y_3(t) \\ y'_1(t) & y'_2(t) & y'_3(t) \\ y''_1(t) & y''_2(t) & y''_3(t) \end{bmatrix}$

That is

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -r(t) & -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix} \quad (**)$$

Each solution y_i to (*) gives a solution $\begin{bmatrix} y_i \\ y'_i \\ y''_i \end{bmatrix}$ to system (**)

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To solve system (**), try $\mathbf{x}(t) = \Phi(t)\mathbf{c}(t)$

That is

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -r(t) & -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix} \quad (**)$$

Each solution y_i to (*) gives a solution $\begin{bmatrix} y_i \\ y'_i \\ y''_i \end{bmatrix}$ to system (**)

Fundamental matrix $\Phi(t) = \begin{bmatrix} y_1(t) & y_2(t) & y_3(t) \\ y'_1(t) & y'_2(t) & y'_3(t) \\ y''_1(t) & y''_2(t) & y''_3(t) \end{bmatrix}$

To solve system (**), try $\mathbf{x}(t) = \Phi(t)\mathbf{c}(t)$

Substitute and simplify

That is

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -r(t) & -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix} \quad (**)$$

Each solution y_i to (*) gives a solution $\begin{bmatrix} y_i \\ y'_i \\ y''_i \end{bmatrix}$ to system (**)

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To solve system (**), try $\mathbf{x}(t) = \Phi(t)\mathbf{c}(t)$

Substitute and simplify $\Phi(t)\mathbf{c}'(t) = \mathbf{g}(t)$

That is

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -r(t) & -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix} \quad (**)$$

Each solution y_i to (*) gives a solution $\begin{bmatrix} y_i \\ y'_i \\ y''_i \end{bmatrix}$ to system (**)

Fundamental matrix $\Phi(t) = \begin{bmatrix} y_1(t) & y_2(t) & y_3(t) \\ y'_1(t) & y'_2(t) & y'_3(t) \\ y''_1(t) & y''_2(t) & y''_3(t) \end{bmatrix}$

To solve system (**), try $\mathbf{x}(t) = \Phi(t)\mathbf{c}(t)$

Substitute and simplify $\Phi(t)\mathbf{c}'(t) = \mathbf{g}(t)$

That is,

$$\begin{bmatrix} y_1(t) & y_2(t) & y_3(t) \\ y'_1(t) & y'_2(t) & y'_3(t) \\ y''_1(t) & y''_2(t) & y''_3(t) \end{bmatrix} \begin{bmatrix} c'_1(t) \\ c'_2(t) \\ c'_3(t) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ g(t) \end{bmatrix}$$