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- Find eigenvalue(s) solve $\det(\mathbf{A} - \lambda\mathbf{I}) = 0$

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Subcase (2,2) Two linearly independent eigenvectors $\mathbf{v}^{(1)}$ and $\mathbf{v}^{(2)}$

Subcase (2,1) Only one linearly independent eigenvector \mathbf{v}

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Two linearly independent solutions to system

$$\mathbf{x}^{(1)}(t) = \mathbf{v}^{(1)}e^{rt}, \quad \mathbf{x}^{(2)}(t) = \mathbf{v}^{(2)}e^{rt}$$

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Two linearly independent solutions to system

$$\mathbf{x}^{(1)}(t) = \mathbf{v}e^{rt}, \quad \mathbf{x}^{(2)}(t) = (\mathbf{v}t + \mathbf{u})e^{rt}$$

Sub-case (3,3) $A.M. = 3, G.M. = 3$

- Associated to eigenvalue $r \in \mathbb{R}$, there are 3 linearly independent eigenvectors $\mathbf{v}^{(1)}, \mathbf{v}^{(2)}, \mathbf{v}^{(3)} \in \mathbb{R}^n$

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- Get three solutions

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$$\mathbf{x}^{(3)}(t) = \mathbf{v}^{(3)}e^{rt}$$

They are linearly independent because $W(0) \neq 0$

Sub-case (3,1) $A.M. = 3$, $G.M. = 1$

Associated to eigenvalue $r \in \mathbb{R}$, *only one* linearly independent eigenvector $\in \mathbb{R}^n$

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Note that $(\mathbf{A} - r\mathbf{I})^2\mathbf{w} = (\mathbf{A} - r\mathbf{I})\mathbf{u}$

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Note that $(\mathbf{A} - r\mathbf{I})^2\mathbf{w} = (\mathbf{A} - r\mathbf{I})\mathbf{u} = \mathbf{v}$ $(\mathbf{A} - r\mathbf{I})^3\mathbf{w} = (\mathbf{A} - r\mathbf{I})\mathbf{v} = \mathbf{0}$

Therefore,
$$e^{\mathbf{A}t}\mathbf{w} = e^{rt} \left(\mathbf{I} + t(\mathbf{A} - r\mathbf{I}) + \frac{t^2}{2}(\mathbf{A} - r\mathbf{I})^2 + \frac{t^3}{3!}(\mathbf{A} - r\mathbf{I})^3 + \dots \right) \mathbf{w}$$

Therefore,
$$\begin{aligned} e^{\mathbf{A}t}\mathbf{w} &= e^{rt} \left(\mathbf{I} + t(\mathbf{A} - r\mathbf{I}) + \frac{t^2}{2}(\mathbf{A} - r\mathbf{I})^2 + \frac{t^3}{3!}(\mathbf{A} - r\mathbf{I})^3 + \dots \right) \mathbf{w} \\ &= e^{rt} \left(\mathbf{w} + t(\mathbf{A} - r\mathbf{I})\mathbf{w} + \frac{t^2}{2}(\mathbf{A} - r\mathbf{I})^2\mathbf{w} \right) \end{aligned}$$

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 &= e^{rt} \left(\mathbf{w} + t\mathbf{u} + \frac{t^2}{2}\mathbf{v} \right)
 \end{aligned}$$

Third solution $\mathbf{x}^{(3)}(t) = \mathbf{v}\frac{t^2}{2!}e^{rt} + \mathbf{u}te^{rt} + \mathbf{w}e^{rt}$

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Remark \mathbf{u} and \mathbf{w} can be solved because

$$\ker(\mathbf{A} - r\mathbf{I}) \subsetneq \ker(\mathbf{A} - r\mathbf{I})^2 \subsetneq \ker(\mathbf{A} - r\mathbf{I})^3$$

Therefore,

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$\mathbf{x}^{(1)}(t)$, $\mathbf{x}^{(2)}(t)$ and $\mathbf{x}^{(3)}(t)$ are linearly independent

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$\mathbf{x}^{(1)}(t)$, $\mathbf{x}^{(2)}(t)$ and $\mathbf{x}^{(3)}(t)$ are linearly independent

$$\therefore W[\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \mathbf{x}^{(3)}](0) = \det \begin{bmatrix} \mathbf{v} & \mathbf{u} & \mathbf{w} \end{bmatrix}$$

Therefore,

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 e^{\mathbf{A}t}\mathbf{w} &= e^{rt} \left(\mathbf{I} + t(\mathbf{A} - r\mathbf{I}) + \frac{t^2}{2}(\mathbf{A} - r\mathbf{I})^2 + \frac{t^3}{3!}(\mathbf{A} - r\mathbf{I})^3 + \dots \right) \mathbf{w} \\
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$\mathbf{x}^{(1)}(t)$, $\mathbf{x}^{(2)}(t)$ and $\mathbf{x}^{(3)}(t)$ are linearly independent

$$\begin{aligned}
 \because W[\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \mathbf{x}^{(3)}](0) &= \det \begin{bmatrix} \mathbf{v} & \mathbf{u} & \mathbf{w} \end{bmatrix} \\
 &\neq 0
 \end{aligned}$$

The vectors \mathbf{v} , \mathbf{u} and \mathbf{w} are linearly independent.

Proof

The vectors \mathbf{v} , \mathbf{u} and \mathbf{w} are linearly independent.

Proof Suppose $a\mathbf{v} + b\mathbf{u} + c\mathbf{w} = \mathbf{0}$ (1)

The vectors \mathbf{v} , \mathbf{u} and \mathbf{w} are linearly independent.

Proof Suppose $a\mathbf{v} + b\mathbf{u} + c\mathbf{w} = \mathbf{0}$ (1)

Apply $(\mathbf{A} - r\mathbf{I})$ $a(\mathbf{A} - r\mathbf{I})\mathbf{v} + b(\mathbf{A} - r\mathbf{I})\mathbf{u} + c(\mathbf{A} - r\mathbf{I})\mathbf{w} = \mathbf{0}$

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By construction $b\mathbf{v} + c\mathbf{u} = \mathbf{0}$ (2)

The vectors \mathbf{v} , \mathbf{u} and \mathbf{w} are linearly independent.

Proof Suppose $a\mathbf{v} + b\mathbf{u} + c\mathbf{w} = \mathbf{0}$ (1)

$$\text{Apply } (\mathbf{A} - r\mathbf{I}) \quad a(\mathbf{A} - r\mathbf{I})\mathbf{v} + b(\mathbf{A} - r\mathbf{I})\mathbf{u} + c(\mathbf{A} - r\mathbf{I})\mathbf{w} = \mathbf{0}$$

$$\text{By construction} \quad b\mathbf{v} + c\mathbf{u} = \mathbf{0} \quad (2)$$

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$$\text{Apply } (\mathbf{A} - r\mathbf{I}) \quad b(\mathbf{A} - r\mathbf{I})\mathbf{v} + c(\mathbf{A} - r\mathbf{I})\mathbf{u} = \mathbf{0}$$

$$\text{By construction} \quad c\mathbf{v} = \mathbf{0} \quad (3)$$

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By construction $c\mathbf{v} = \mathbf{0}$ (3)

From (3), (2) and (1), get $c = 0$, $b = 0$ and $a = 0$

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From (3), (2) and (1), get $c = 0$, $b = 0$ and $a = 0$

Terminology \mathbf{v} is an **eigenvector** and \mathbf{u} and \mathbf{w} are *generalized eigenvectors*.

The vectors \mathbf{v} , \mathbf{u} and \mathbf{w} are linearly independent.

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From (3), (2) and (1), get $c = 0$, $b = 0$ and $a = 0$

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Solutions to system using chain of generalized eigenvectors

Consider the system $\mathbf{x}'(t) = \mathbf{A}\mathbf{x}(t)$

(1) $\mathbf{x}(t) = \mathbf{v}e^{rt}$ is a solution $\iff (\mathbf{A} - r\mathbf{I})\mathbf{v} = \mathbf{0}$ $r \in \mathbb{R}$, $\mathbf{v} \in \mathbb{R}^n$

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That is $\langle \mathbf{v}, \mathbf{y} \rangle = 0$ for all \mathbf{y} satisfying $(\mathbf{A}^T - r\mathbf{I})\mathbf{y} = \mathbf{0}$

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\mathbf{v} is a non-trivial linear combination of \mathbf{v}_1 and \mathbf{v}_2 $\mathbf{v} = c_1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$

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Third solution $\mathbf{x}^{(3)}(t) = \begin{bmatrix} 1 & -1 & -1 \end{bmatrix}^T te^t + \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^T e^t$

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Use Theorem $\langle \mathbf{v}, \mathbf{y} \rangle = 0$ for all \mathbf{y} belonging to the *kernel* of $(\mathbf{A}^T - \mathbf{I})$

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Continue ...

Remark

- Subcase (3,1) to find chain of generalized eigenvectors $(\mathbf{v}, \mathbf{u}, \mathbf{w})$, solve

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can be found *without solving* $(\mathbf{A} - \alpha\mathbf{I})\mathbf{v} = \mathbf{0}$