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  - ◇ **Undetermined coefficients** particular solution  $y_p(t) = t^2Ae^{-2t}$

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# *n*th Order Linear DE/IVP

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## Chapter 3: First Order Systems

- (1) E & U Theorem
- (2) Linear Systems
- (3) Homogeneous Systems with Constant Coefficients
  - Elimination
  - Matrix Exponential
  - Eigenvalues Method
- (4) Non-homogeneous Systems
  - Undetermined Coefficients
  - Variation of Parameters

*First Order System* (explicit form,  $n$  equations,  $n$  unknown functions)

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*Solutions* to the system in an open interval  $(a, b)$  expressed in the form

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for each  $i = 1, 2, \dots, n$ ,  $\varphi'_i(t) = F_i(t, \varphi_1(t), \varphi_2(t), \dots, \varphi_n(t)) \quad \forall t \in (a, b)$

## 1st order system IVP

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$$(t_0, x_1^0, x_2^0, \dots, x_n^0) \in \text{dom } F_i \quad \text{for all } i = 1, \dots, n$$

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Let  $f_i : (a, b) \rightarrow \mathbb{R}$  ( $i = 1, \dots, n$ ) be (real-valued) functions.

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- Similarly, can define
  - ◇ vector-valued functions of *several variables*.

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Define *derivative of  $\mathbf{f}$*   $\mathbf{f}' : (a, b) \longrightarrow \mathbb{R}^n$   $\mathbf{f}'(t) = \begin{bmatrix} f'_1(t) \\ \vdots \\ f'_n(t) \end{bmatrix}$

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$$\text{System} \left\{ \begin{array}{l} x'_1 = F_1(t, x_1, \dots, x_n) \\ x'_2 = F_2(t, x_1, \dots, x_n) \\ \vdots \\ x'_n = F_n(t, x_1, \dots, x_n), \end{array} \right.$$

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**Corollary** Consider the  $n$ th order IVP

$$\begin{cases} y^{(n)} = F(t, y, y', \dots, y^{(n-1)}), \\ y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)} \end{cases}$$

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Using induction,

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Solution to original IVP  $y(t) = \cos t$

# First order Linear systems

## First order Linear systems

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**First order Linear systems**      each  $F_i$  "*linear*" in  $x_1, x_2, \dots, x_n$

$$\left\{ \begin{array}{l} x'_1 = p_{11}(t)x_1 + \cdots + p_{1n}(t)x_n + g_1(t), \\ \quad \quad \quad \vdots \\ x'_n = p_{n1}(t)x_1 + \cdots + p_{nn}(t)x_n + g_n(t), \end{array} \right. \quad a < t < b$$

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Consider the following system IVP

$$\begin{cases} \mathbf{x}' = \mathbf{P}(t)\mathbf{x} + \mathbf{g}(t), & a < t < b \\ \mathbf{x}(t_0) = \mathbf{x}^0. \end{cases}$$

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- In what follows,  $\mathbf{P}$  and  $\mathbf{g}$  are assumed to be *continuous*.

**Theorem** If  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(k)}$  are solutions to the *homogeneous* system

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then linear combinations of  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(k)}$  are also solutions.

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**Question**  $\dim(\text{solution space}) = ?$