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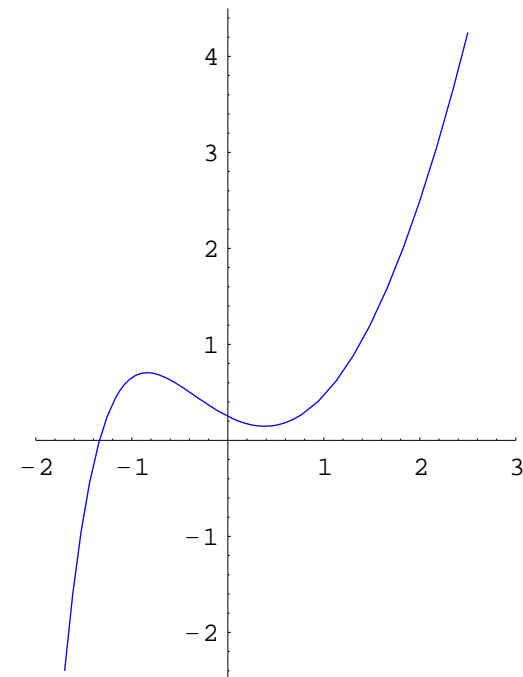
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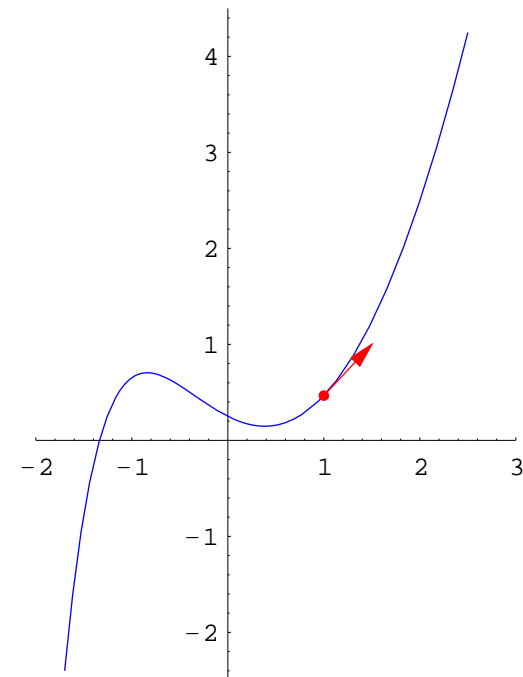
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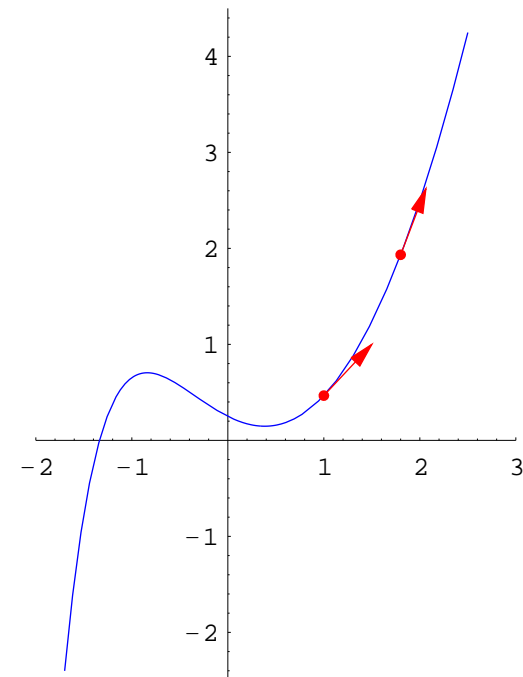
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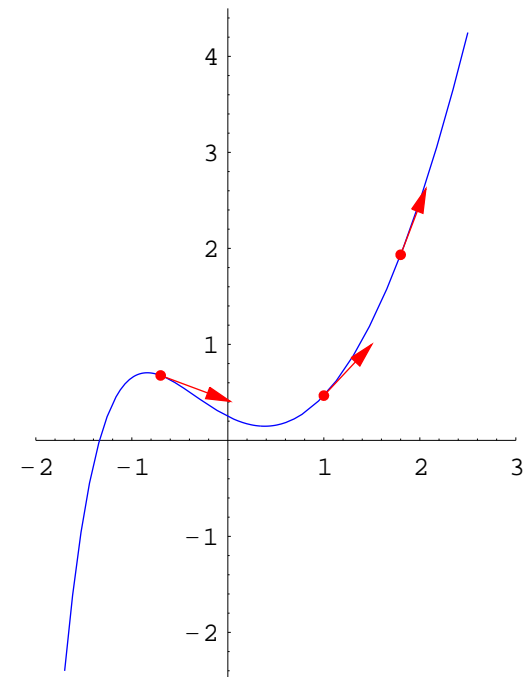
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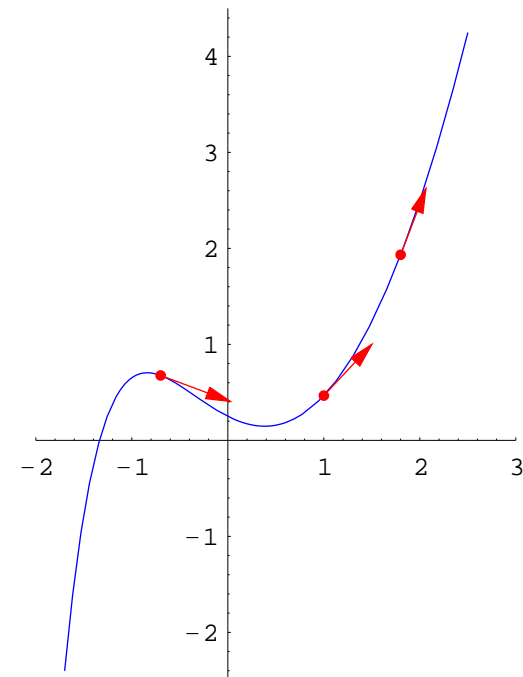
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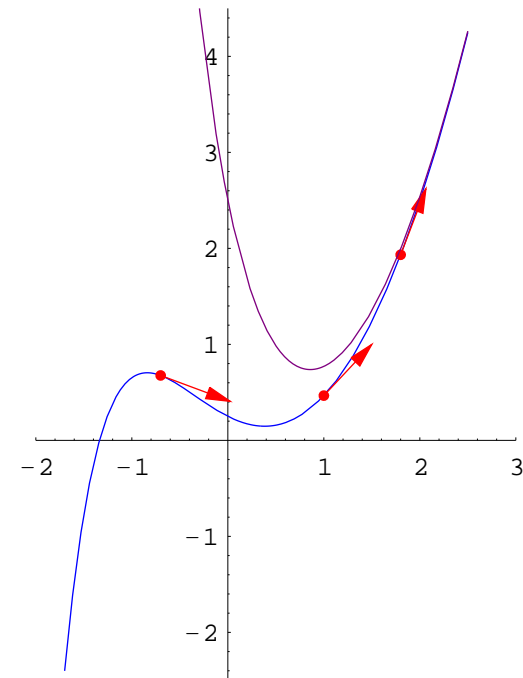
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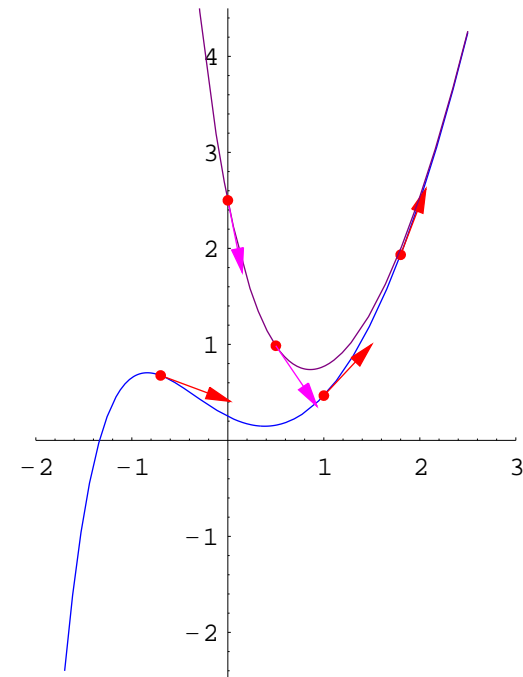
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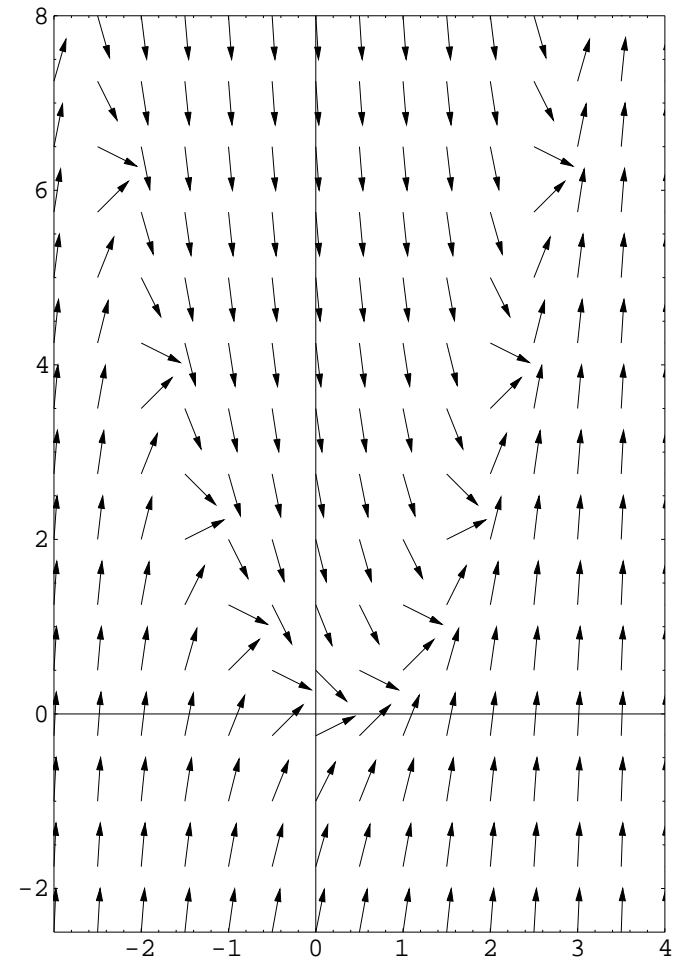


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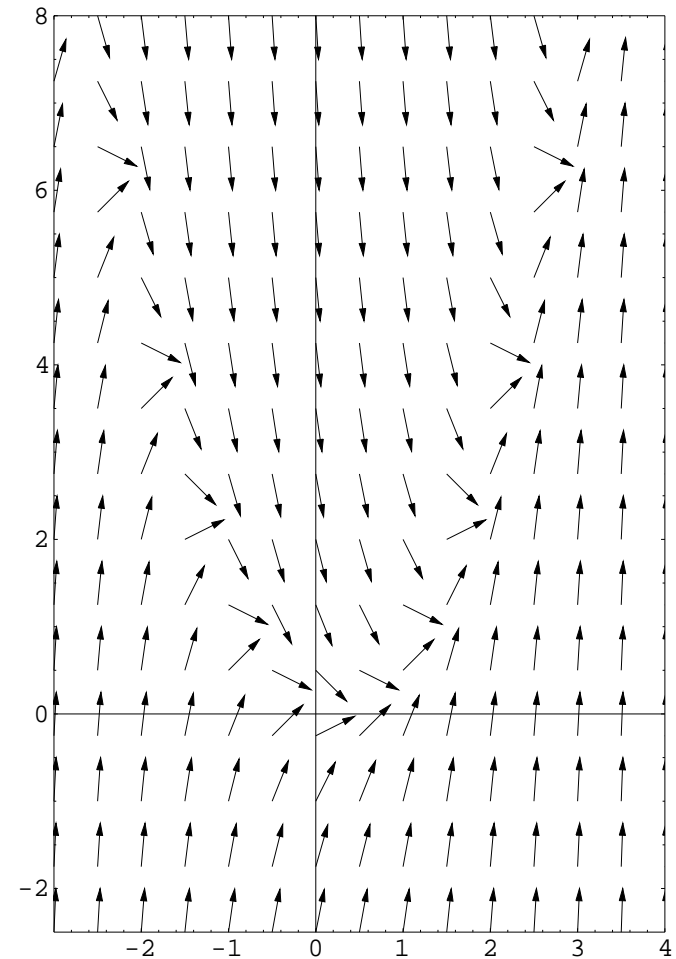
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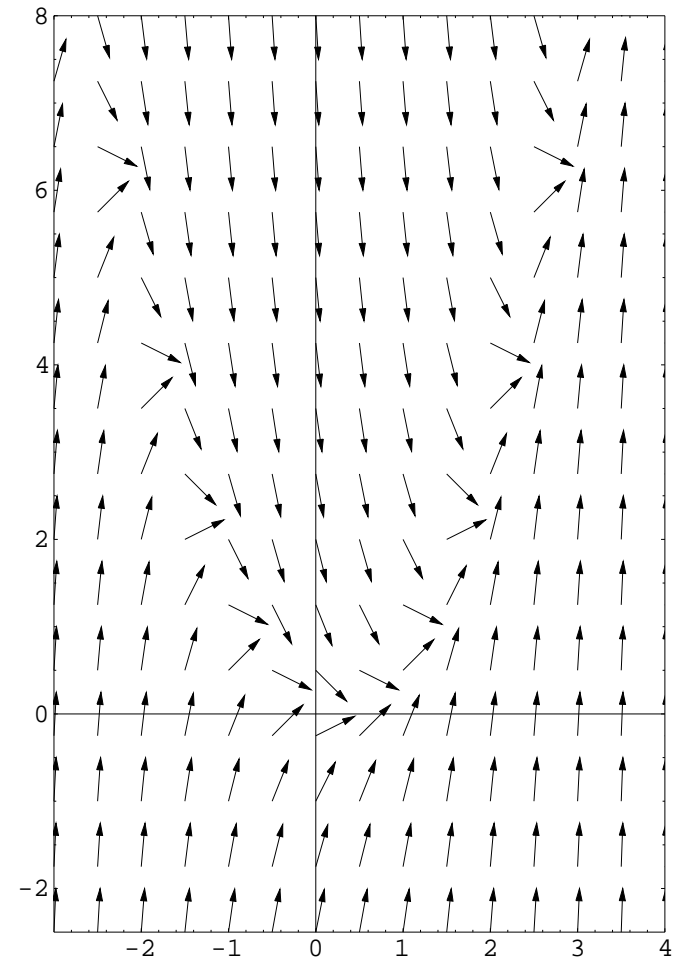
- At each point (t, y) in the ty -plane, draw a short directed line segment with slope $f(t, y)$.
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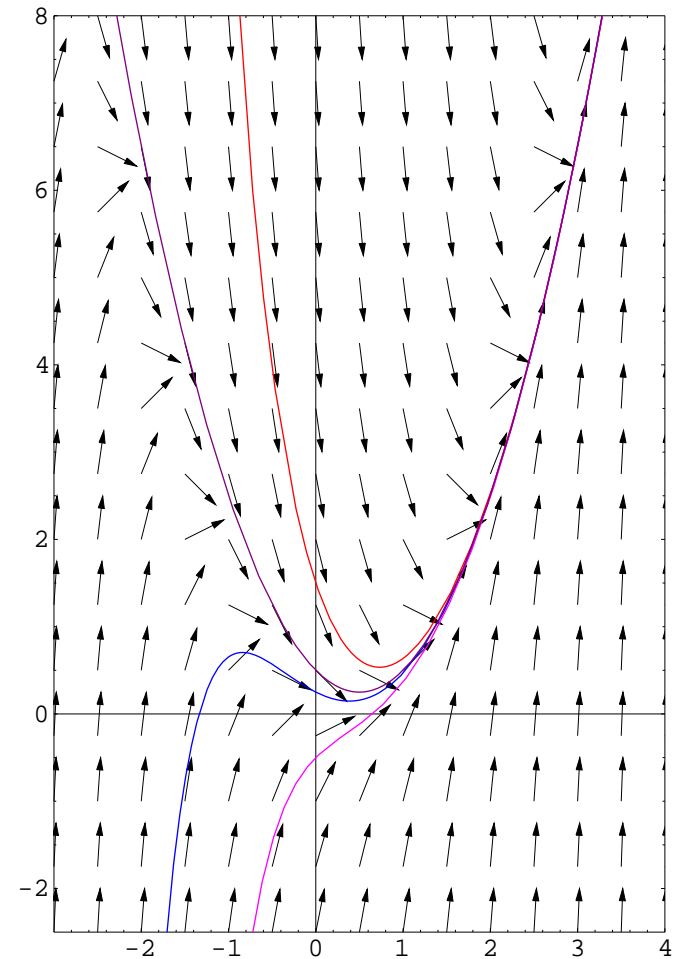
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Piecewise linear approximation

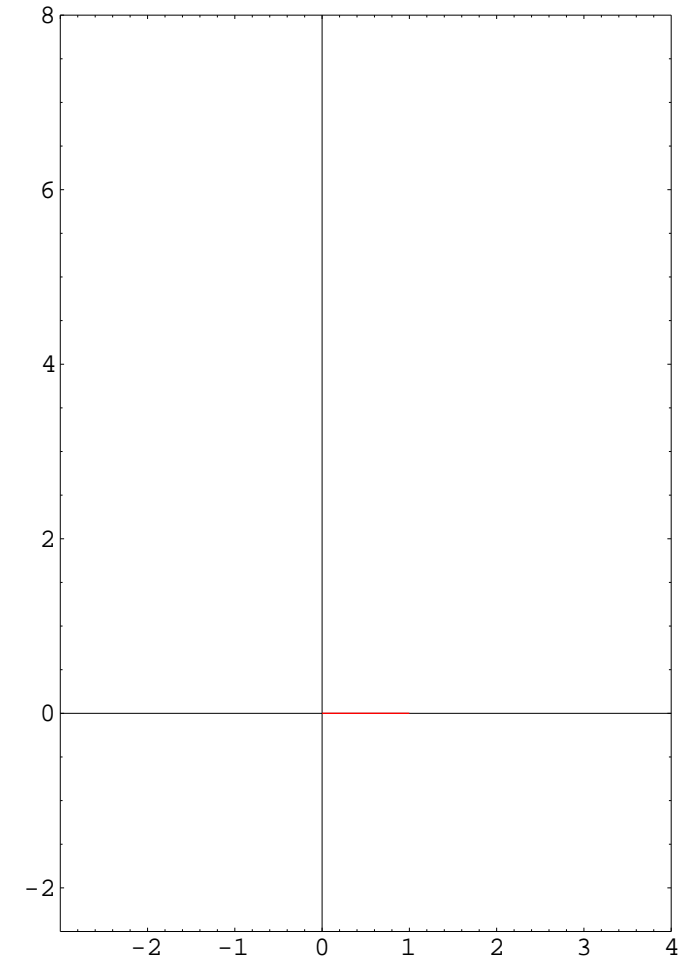
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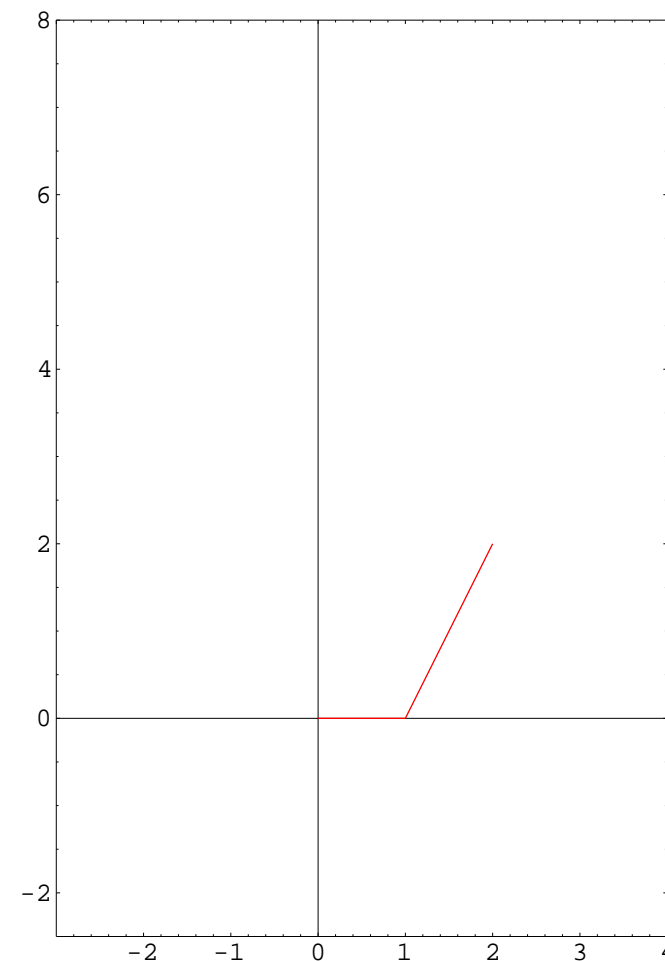


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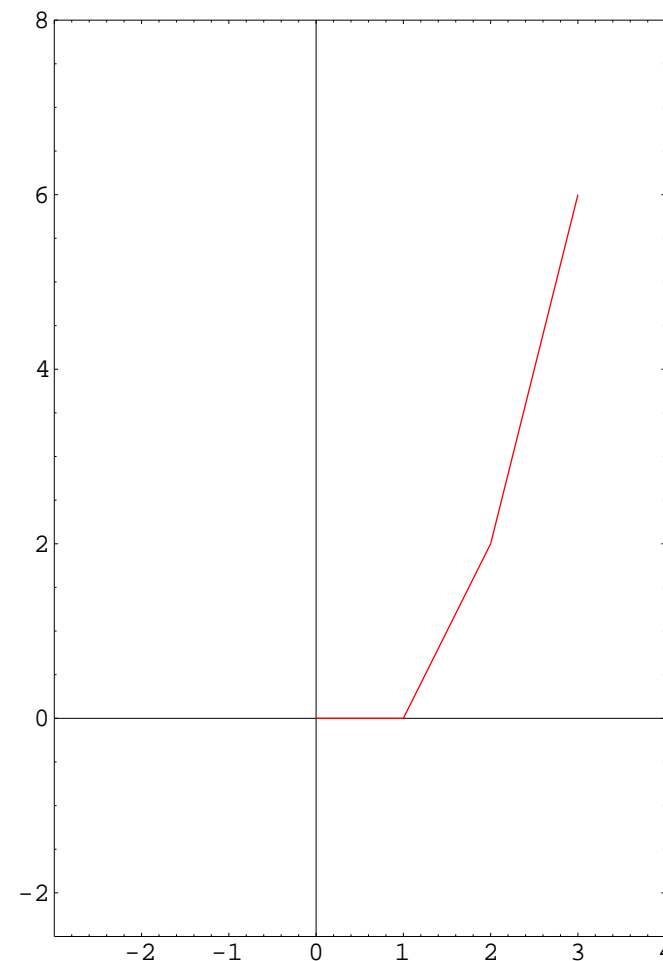


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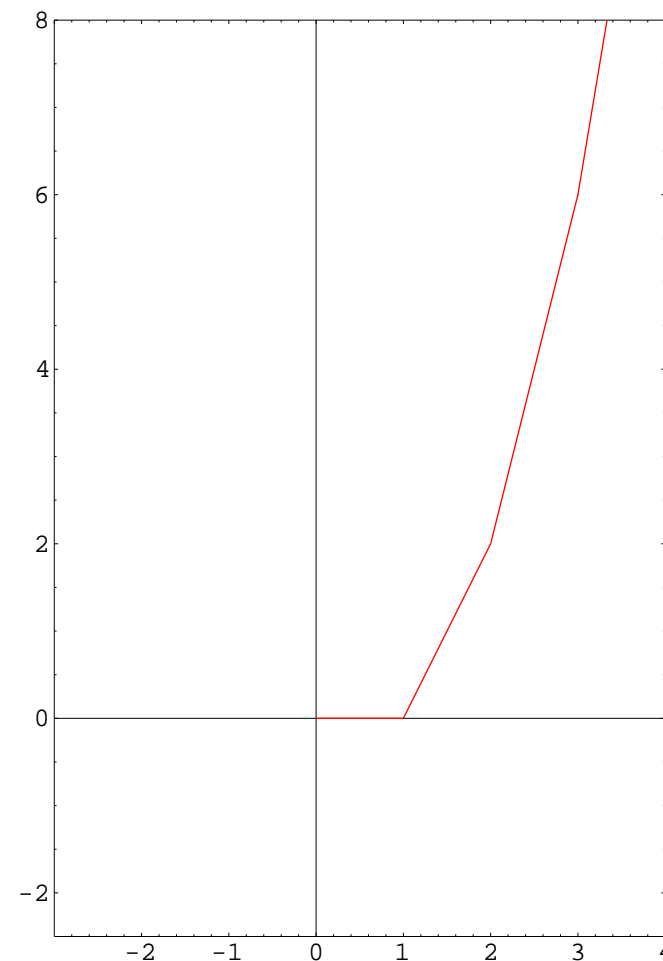


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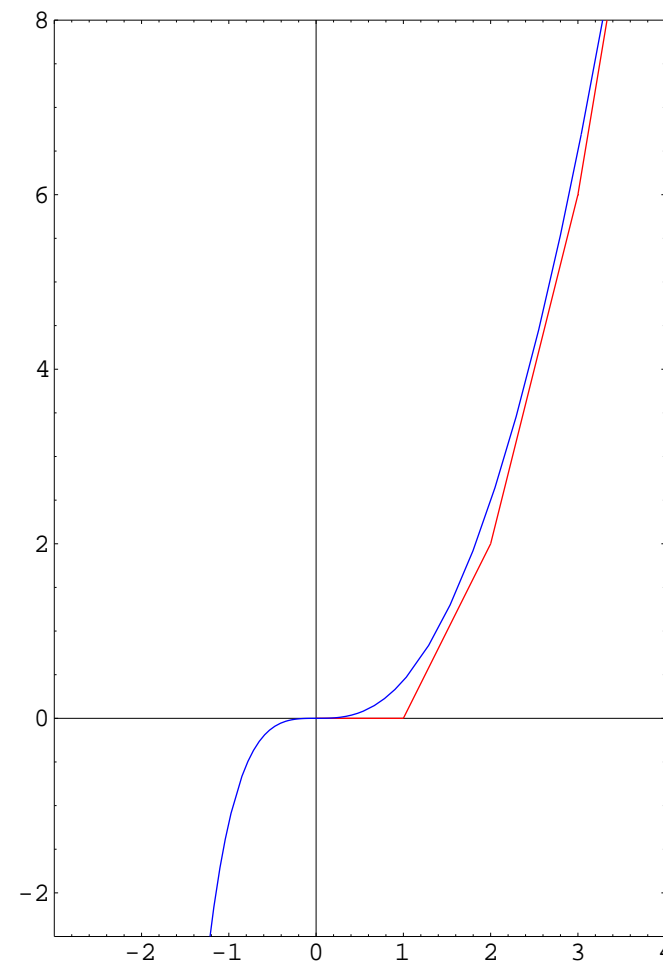


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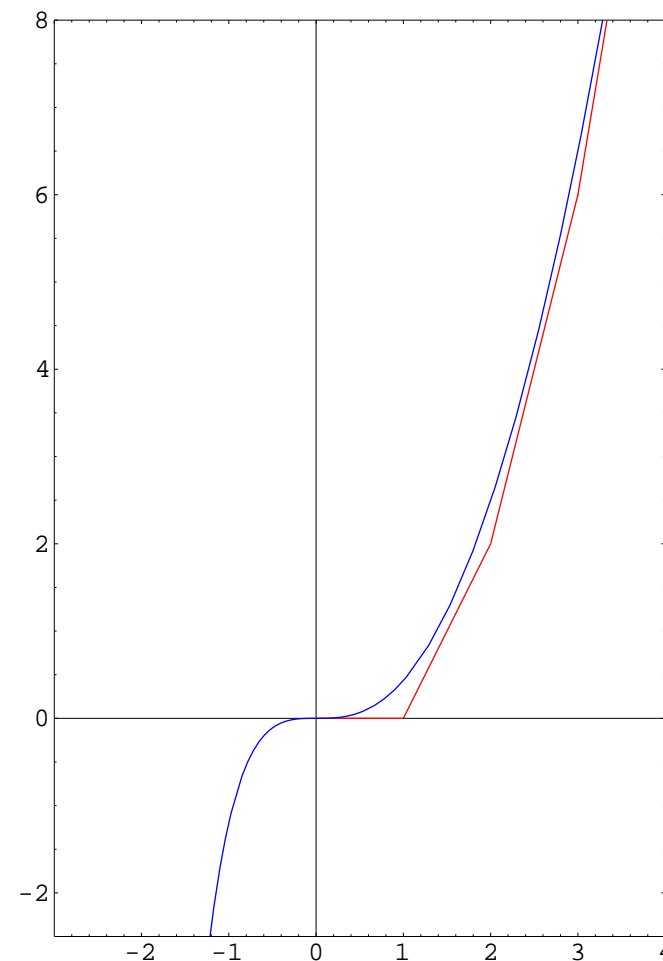
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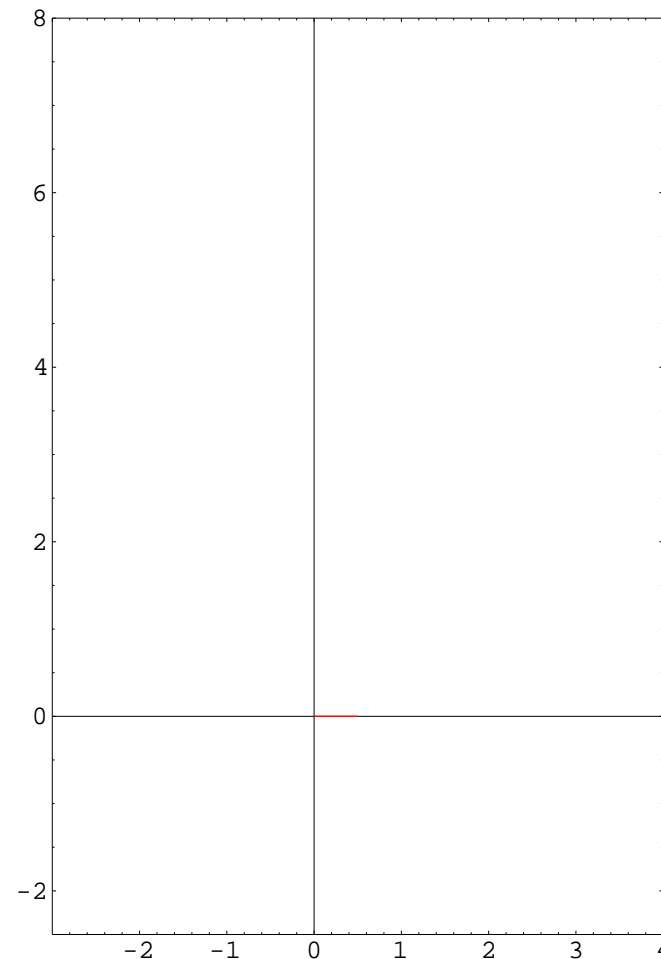
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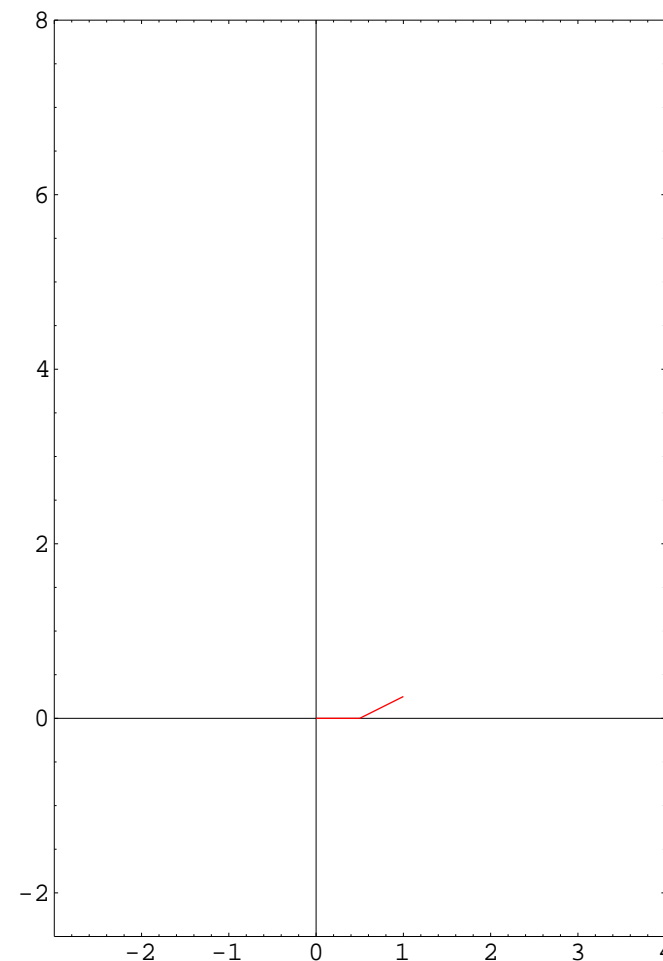
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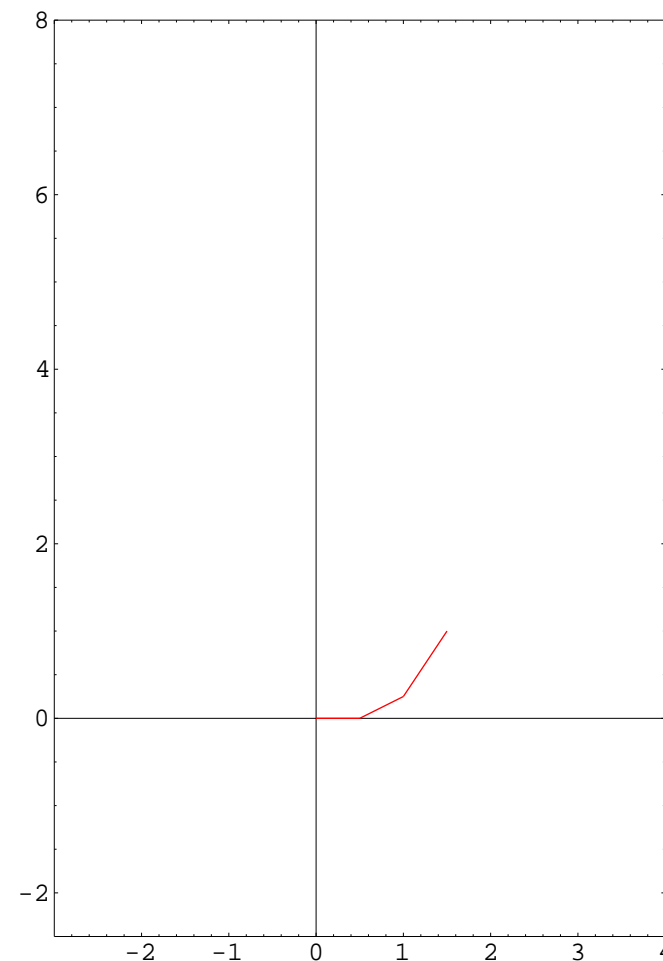
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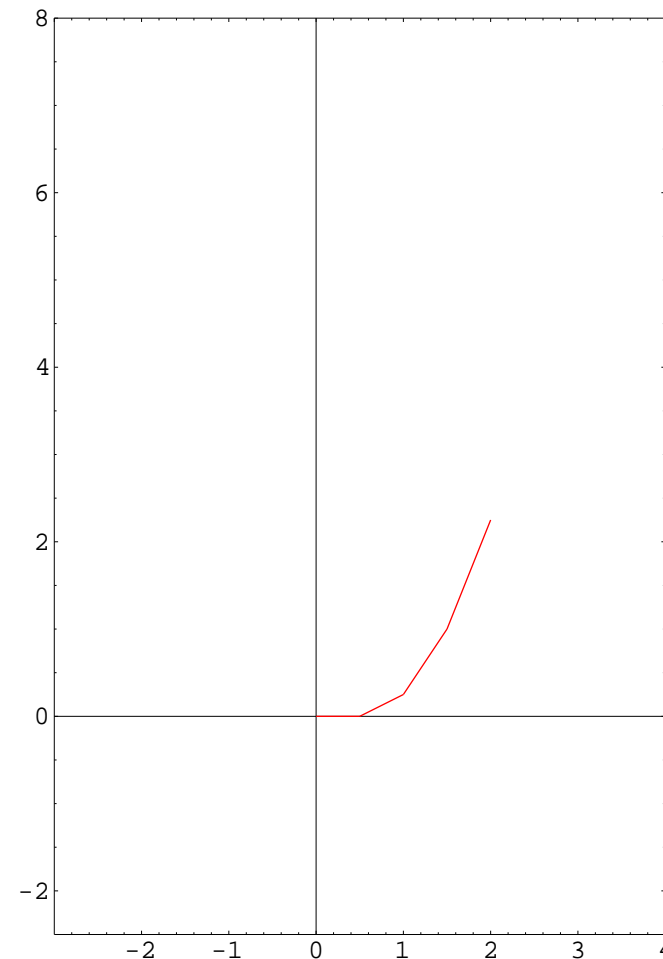
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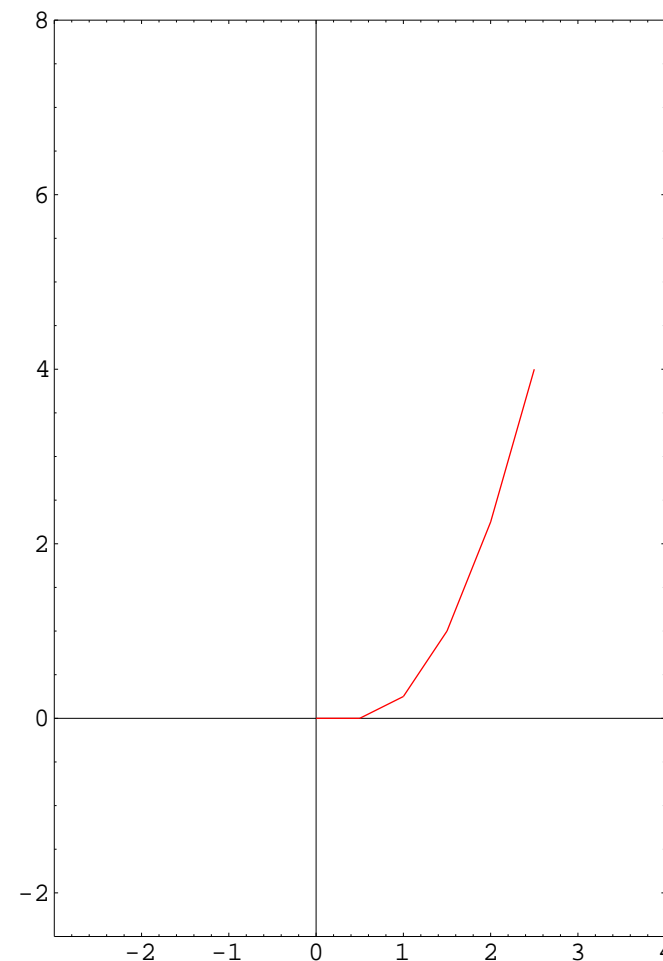
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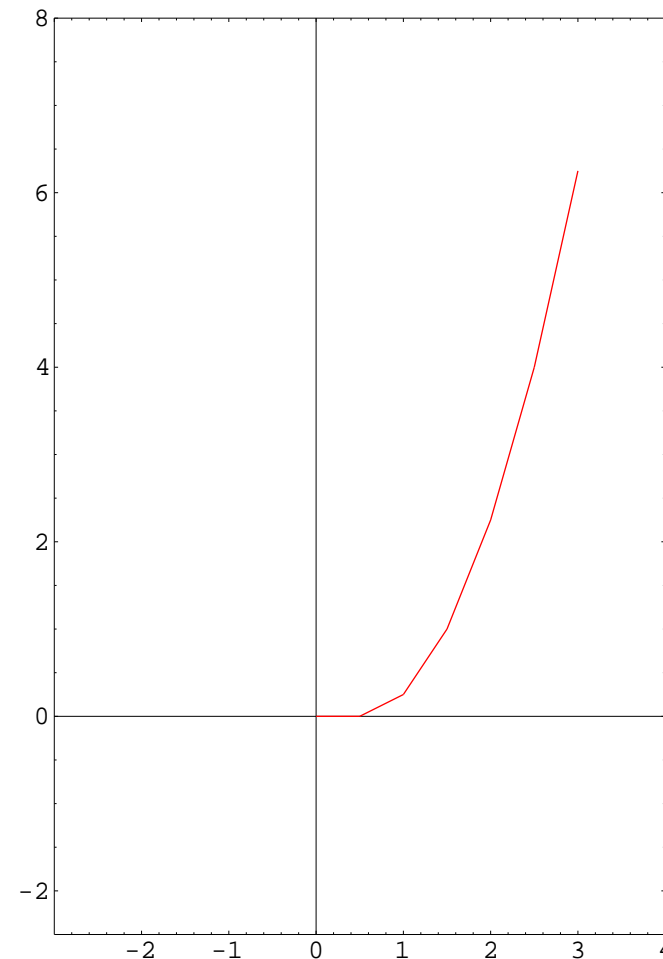
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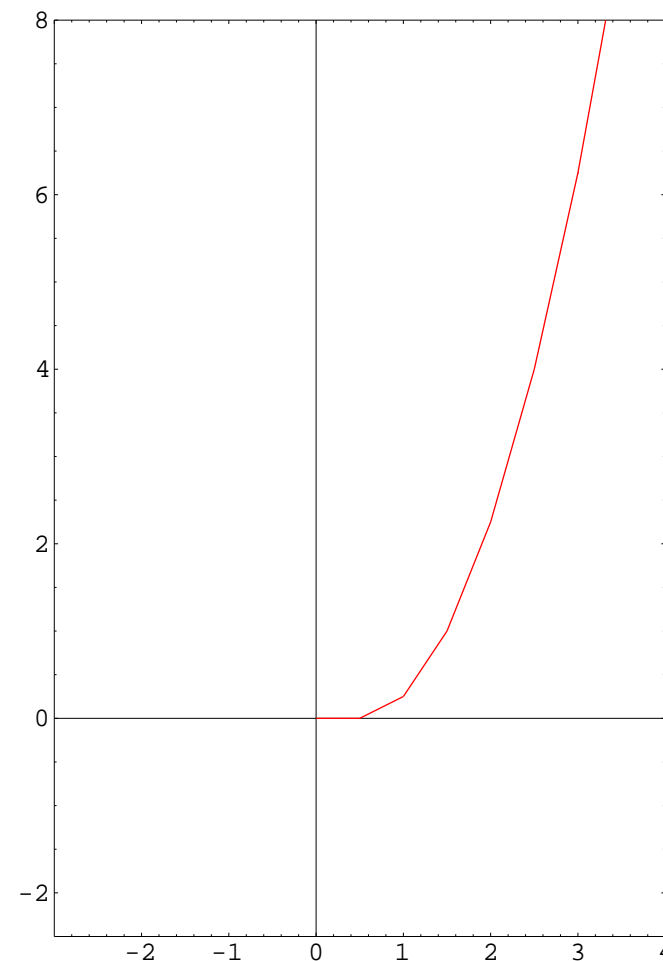
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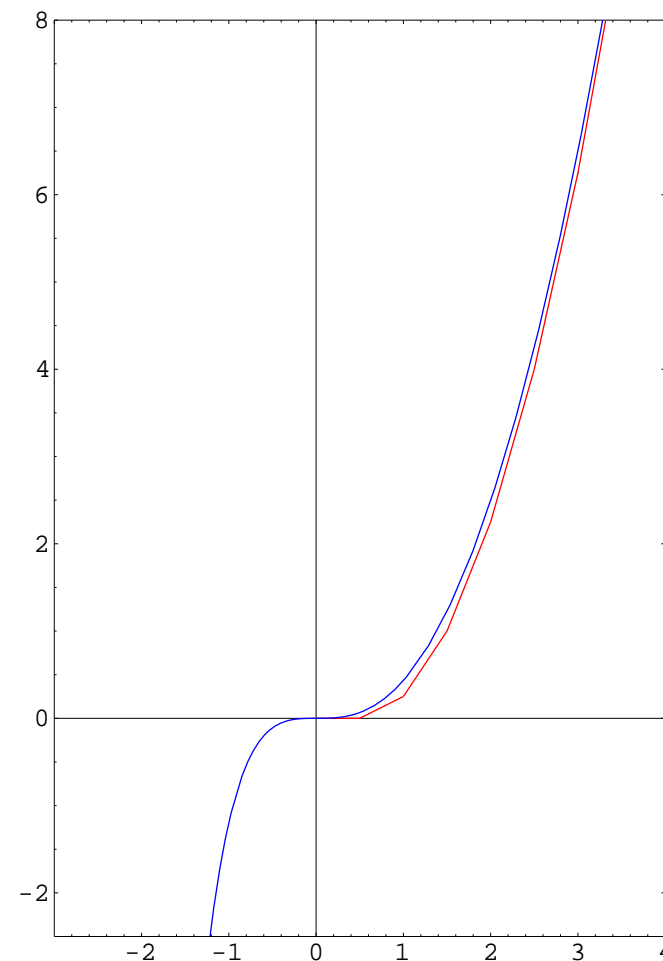
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F is called a *potential function* for \mathbf{f} .

Example

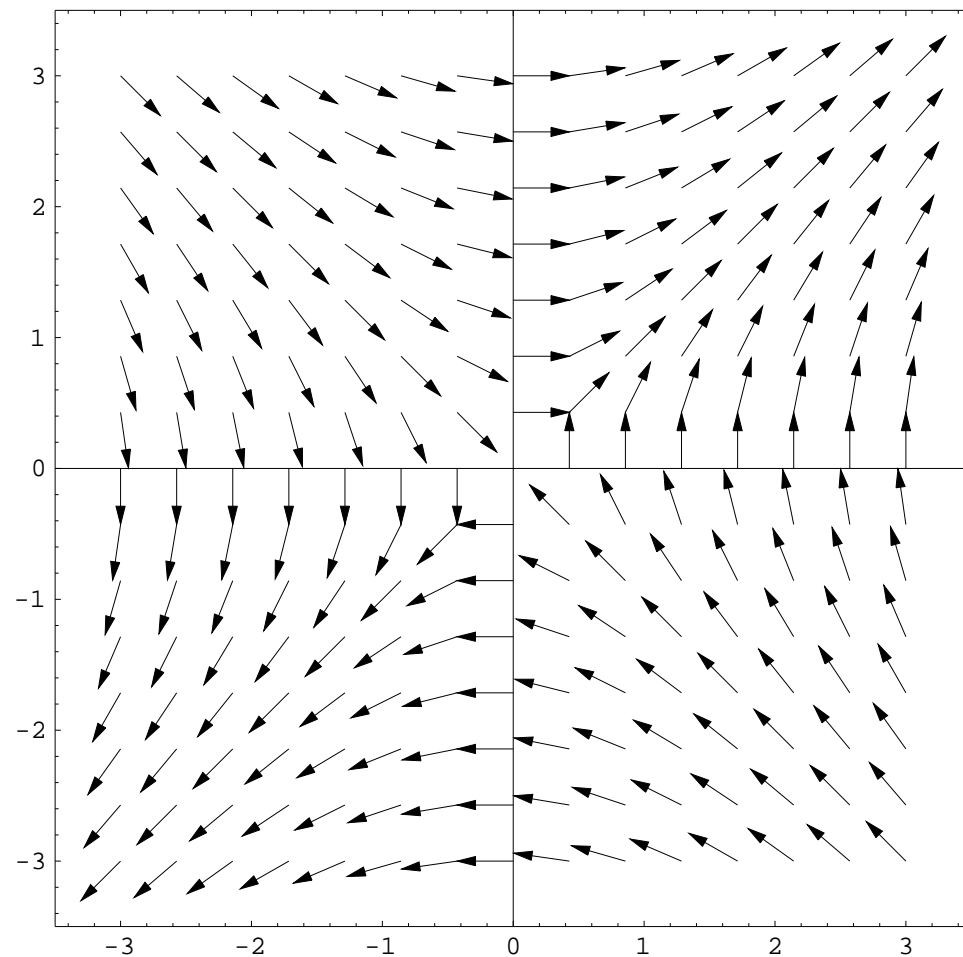
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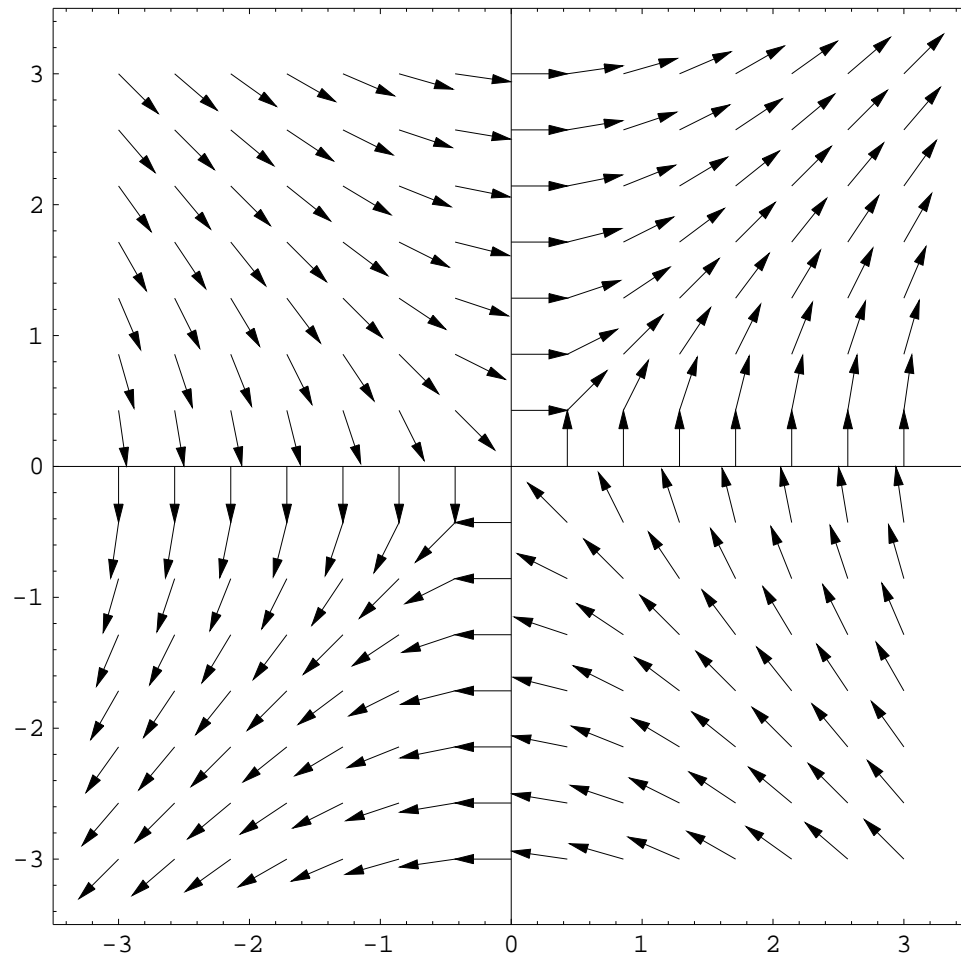
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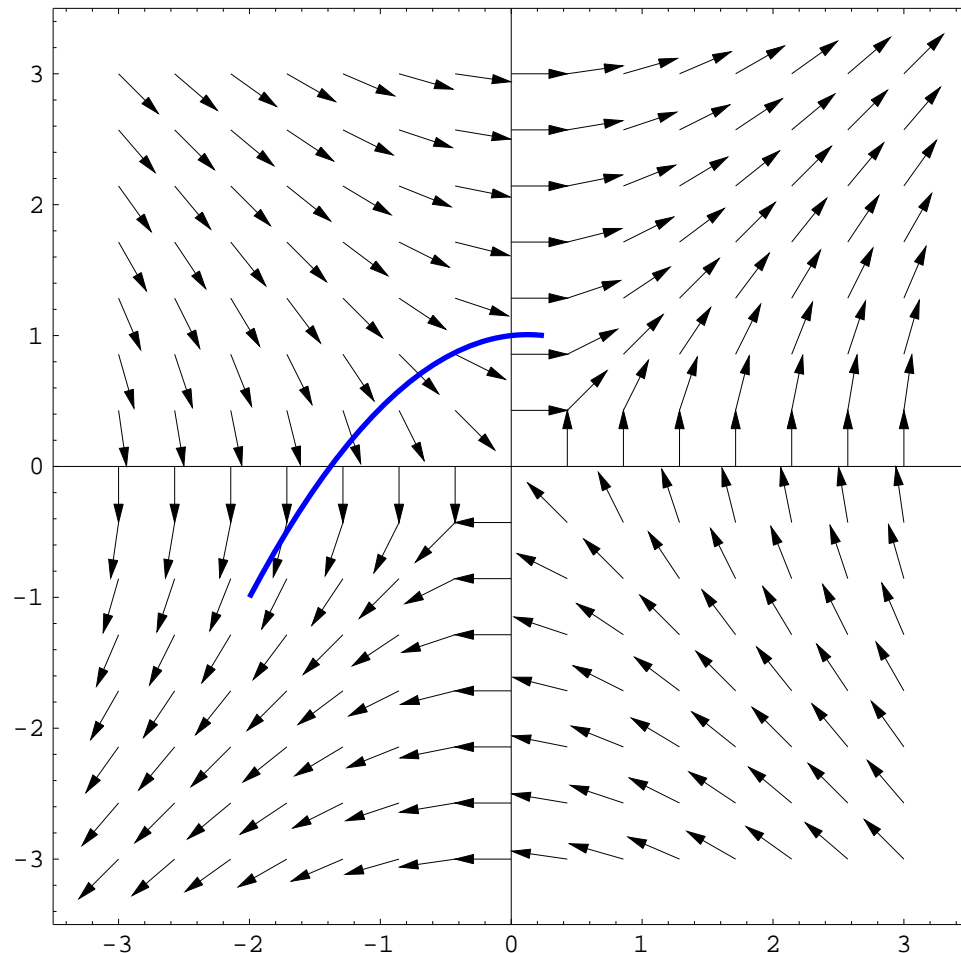
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- Suppose \mathbf{f} is force.
Work done along a path γ is $\int_{\gamma} \mathbf{f} \cdot d\mathbf{y}$



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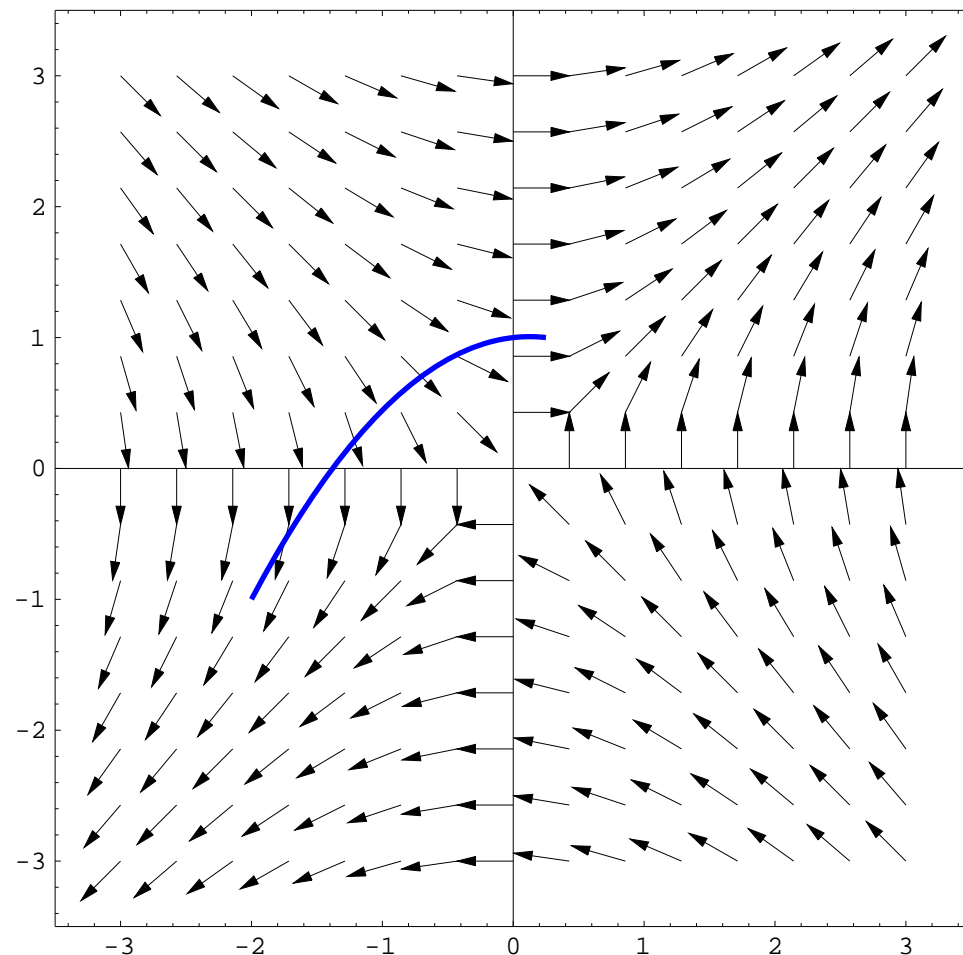
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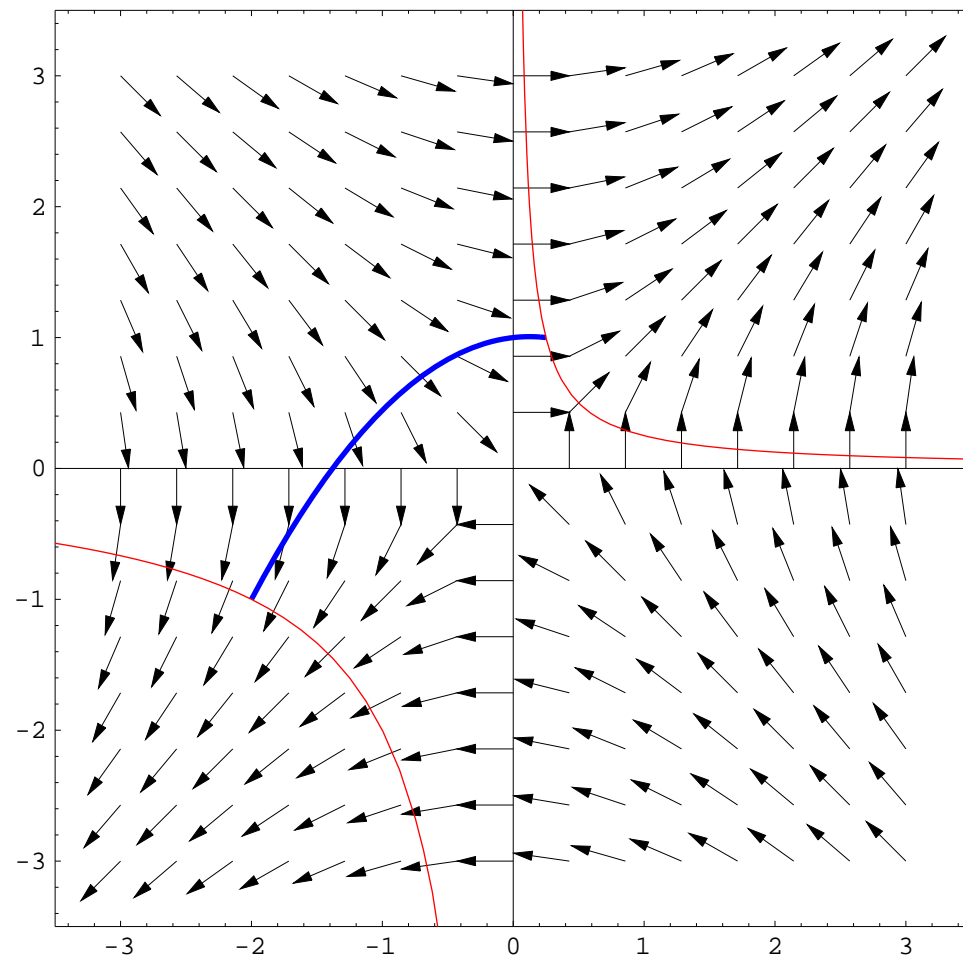
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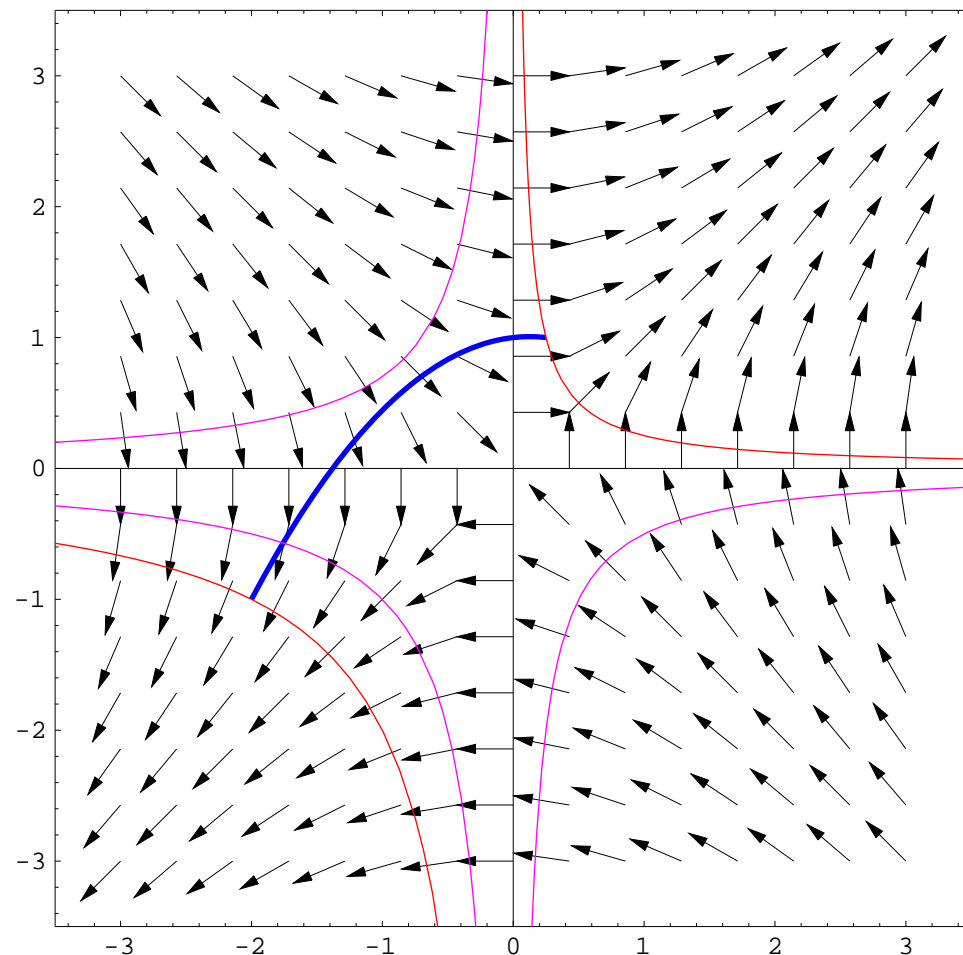
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Chapter 2: Second Order Differential Equations

2.1 Second Order Linear Homogeneous DE

2nd order linear DE

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- ◇ *With abuse of notation*, it is also denoted by p , that is, $p[y] = p \cdot y$.

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Write $L = D^2 + pD + q : C^2(a, b) \longrightarrow C(a, b)$, DE takes the form

$$L[y] = g$$

Proposition $L : C^2(a, b) \longrightarrow C(a, b)$ is *linear*, that is,

$$L[c_1u_1 + c_2u_2] = c_1L[u_1] + c_2L[u_2]$$

for all $u_1, u_2 \in C^2(a, b)$, $c_1, c_2 \in \mathbb{R}$.

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Reason

- $L : C^2(a, b) \longrightarrow C(a, b)$ is linear.
- $\{\text{solution to the DE}\} = \text{kernel of } L$

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- Putting into DE

$$a\lambda^2 e^{\lambda t} + b\lambda e^{\lambda t} + ce^{\lambda t} = 0$$

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where a, b, c are (real) constants and $a \neq 0$.

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- (1) Let α and β be *constants*. Show that

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General solution $y = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t}$ where c_1 and c_2 are arbitrary constants

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