

# MATH 2405 Differential Equations

## Objectives

- Learn some methods for solving DE
- Understand why the methods work
- Understand the main theorems

# MATH 2405 Differential Equations

## Objectives

- Learn some methods for solving DE
- Understand why the methods work
- Understand the main theorems

# MATH 2405 Differential Equations

## Objectives

- Learn some methods for solving DE
- Understand why the methods work
- Understand the main theorems

# MATH 2405 Differential Equations

## Objectives

- Learn some methods for solving DE
- Understand why the methods work
- Understand the main theorems

# Why study Mathematics

**A joke ?**

[See video](#)

# Why study Mathematics

**A joke ?**      [See video](#)

An astronomer, a physicist and a mathematician are holidaying in Scotland. Glancing from a train window, they observed a black sheep in the middle of a field.

# Why study Mathematics

**A joke ?**      [See video](#)

An astronomer, a physicist and a mathematician are holidaying in Scotland. Glancing from a train window, they observed a black sheep in the middle of a field.

*“How interesting,”* observes the astronomer, *“all Scottish sheep are black !”*

## Why study Mathematics

A joke ? [See video](#)

An astronomer, a physicist and a mathematician are holidaying in Scotland. Glancing from a train window, they observed a black sheep in the middle of a field.

*“How interesting,”* observes the astronomer, *“all Scottish sheep are black !”*

To which the physicist responds, *“No, no! Some Scottish sheep are black !”*



## Why study Mathematics

### A joke ? [See video](#)

An astronomer, a physicist and a mathematician are holidaying in Scotland. Glancing from a train window, they observed a black sheep in the middle of a field.

*“How interesting,”* observes the astronomer, *“all Scottish sheep are black !”*

To which the physicist responds, *“No, no! Some Scottish sheep are black !”*

The mathematician gazes heavenward in supplication, and then intones, *“In Scotland there exists a field, containing a sheep, at least one side of which is black.”*

# Why study Mathematics

## A joke ? [See video](#)

An astronomer, a physicist and a mathematician are holidaying in Scotland. Glancing from a train window, they observed a black sheep in the middle of a field.

*“How interesting,”* observes the astronomer, *“all Scottish sheep are black !”*

To which the physicist responds, *“No, no! Some Scottish sheep are black !”*

The mathematician gazes heavenward in supplication, and then intones, *“In Scotland there exists a field, containing a sheep, at least one side of which is black.”*

*A ridicule or a compliment?*

## Why study Differential Equations

Mathematical models used in

- physical sciences,
- engineering,

## Why study Differential Equations

Mathematical models used in

- physical sciences,
- engineering,
- biological sciences,
- social sciences . . .

## A vector-host epidemic model for BSE

$$\left\{ \begin{array}{l} S'(t) = -(aM(t) + b(1 - M(t)))S(t) \\ D'(t) = aM(t)S(t) \\ M'(t) = cD(t)(1 - M(t)) \\ S(0) = 1, \quad D(0) = 0, \quad M(0) = m \end{array} \right.$$

Data

Year	1986	1987	1988	...	...	...	2001
Cases	0	442	2469	...	...	...	499

## SIR model for SARS

$$\left\{ \begin{array}{l} S'(t) = -aS(t)I(t) \\ I'(t) = aS(t)I(t) - bI(t) \\ R'(t) = bI(t) \\ S(0) = p_0 - 1, \quad I(0) = 1, \quad R(0) = 0 \end{array} \right.$$

# Contents

- Chapter 0 Introduction
  - ◇ Classification of Differential Equations
  - ◇ Solutions to Differential Equations and Initial Value Problems
- Chapter 1 First Order Differential Equations
- Chapter 2 Second Order Differential Equations
- Chapter 3 Systems of First Order Differential Equations
- Chapter 4 Laplace Transform
- Chapter 5 Series Solutions
- Chapter 6 Zeros of solutions (*may be omitted*)

# Contents

- Chapter 0 Introduction
  - ◇ Classification of Differential Equations
  - ◇ Solutions to Differential Equations and Initial Value Problems
- Chapter 1 First Order Differential Equations
- Chapter 2 Second Order Differential Equations
- Chapter 3 Systems of First Order Differential Equations
- Chapter 4 Laplace Transform
- Chapter 5 Series Solutions
- Chapter 6 Zeros of solutions (*may be omitted*)



# Contents

- Chapter 0 Introduction
  - ◇ Classification of Differential Equations
  - ◇ Solutions to Differential Equations and Initial Value Problems
- Chapter 1 **First Order Differential Equations**
- Chapter 2 Second Order Differential Equations
- Chapter 3 Systems of First Order Differential Equations
- Chapter 4 Laplace Transform
- Chapter 5 Series Solutions
- Chapter 6 Zeros of solutions (*may be omitted*)

# Contents

- Chapter 0 Introduction
  - ◇ Classification of Differential Equations
  - ◇ Solutions to Differential Equations and Initial Value Problems
- Chapter 1 First Order Differential Equations
- Chapter 2 **Second Order Differential Equations**
- Chapter 3 Systems of First Order Differential Equations
- Chapter 4 Laplace Transform
- Chapter 5 Series Solutions
- Chapter 6 Zeros of solutions (*may be omitted*)

# Contents

- Chapter 0 Introduction
  - ◇ Classification of Differential Equations
  - ◇ Solutions to Differential Equations and Initial Value Problems
- Chapter 1 First Order Differential Equations
- Chapter 2 Second Order Differential Equations
- Chapter 3 **Systems of First Order Differential Equations**
- Chapter 4 Laplace Transform
- Chapter 5 Series Solutions
- Chapter 6 Zeros of solutions (*may be omitted*)

# Contents

- Chapter 0 Introduction
  - ◇ Classification of Differential Equations
  - ◇ Solutions to Differential Equations and Initial Value Problems
- Chapter 1 First Order Differential Equations
- Chapter 2 Second Order Differential Equations
- Chapter 3 Systems of First Order Differential Equations
- Chapter 4 Laplace Transform
- Chapter 5 Series Solutions
- Chapter 6 Zeros of solutions (*may be omitted*)

# Contents

- Chapter 0 Introduction
  - ◇ Classification of Differential Equations
  - ◇ Solutions to Differential Equations and Initial Value Problems
- Chapter 1 First Order Differential Equations
- Chapter 2 Second Order Differential Equations
- Chapter 3 Systems of First Order Differential Equations
- Chapter 4 Laplace Transform
- Chapter 5 Series Solutions
- Chapter 6 **Zeros of solutions** (*may be omitted*)

## Chapter 0: Introduction

A *differential equation* is an equation that involves an *unknown function and its derivative(s)*.

## Chapter 0: Introduction

A *differential equation* is an equation that involves an *unknown function and its derivative(s)*.

### Example

(1) Radioactive decay equation:

$$\frac{dA}{dt} = -kA \quad (1)$$

- $A = A(t)$  is amount of radioactive substance at time  $t$
- $k$  is decay constant

## Chapter 0: Introduction

A *differential equation* is an equation that involves an *unknown function and its derivative(s)*.

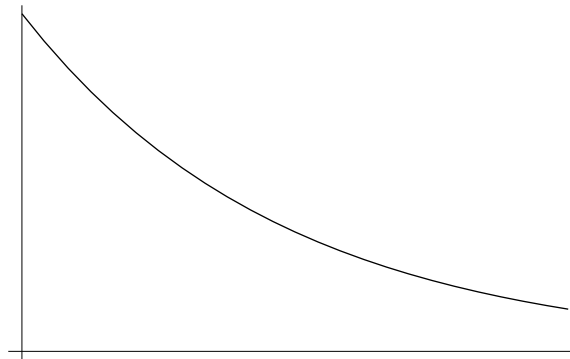
### Example

(1) Radioactive decay equation:

$$\frac{dA}{dt} = -kA \quad (1)$$

- $A = A(t)$  is amount of radioactive substance at time  $t$
- $k$  is decay constant

show decay.nb





(2) Newton's Law of Cooling:

$$\frac{dT}{dt} = -k(T - T^*) \quad (2)$$

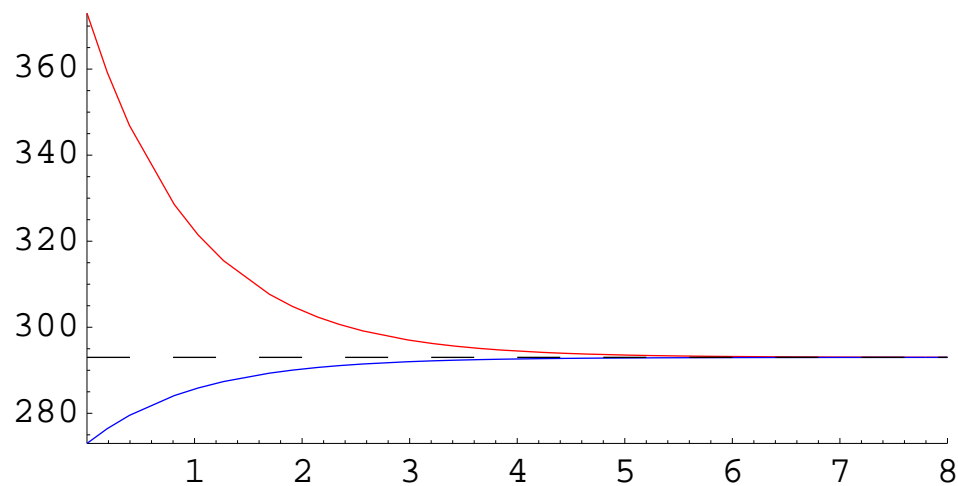
- $T = T(t)$  is temperature of object at time  $t$
- $T^*$  is the temperature of the surrounding
- $k$  is a positive constant

## (2) Newton's Law of Cooling:

$$\frac{dT}{dt} = -k(T - T^*) \quad (2)$$

- $T = T(t)$  is temperature of object at time  $t$
- $T^*$  is the temperature of the surrounding
- $k$  is a positive constant

show cooling.nb



(3) Logistic equation:

$$\frac{dP}{dt} = kP(P^* - P) \quad (3)$$

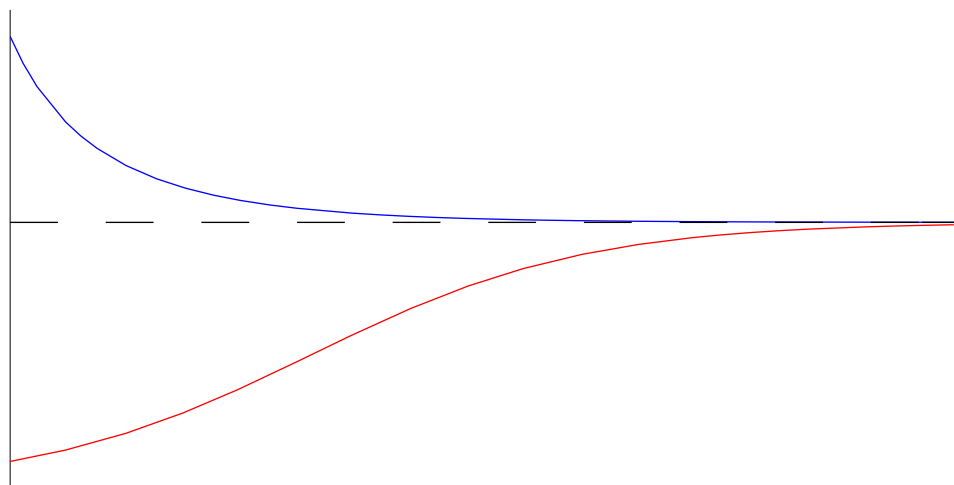
- $P = P(t)$  is population size at time  $t$
- $P^*$  is largest population that environment can support
- $k$  is a positive constant

(3) Logistic equation:

$$\frac{dP}{dt} = kP(P^* - P) \quad (3)$$

- $P = P(t)$  is population size at time  $t$
- $P^*$  is largest population that environment can support
- $k$  is a positive constant

show logistic.nb

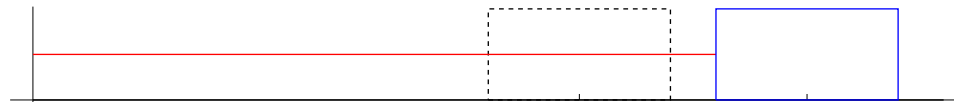


(4) Damped unforced vibration:

$$M \frac{d^2 x}{dt^2} + c \frac{dx}{dt} + kx = 0 \quad (4)$$

- $x = x(t)$  is displacement at time  $t$
- $M =$  mass
- $k =$  spring constant
- $c =$  resistance constant

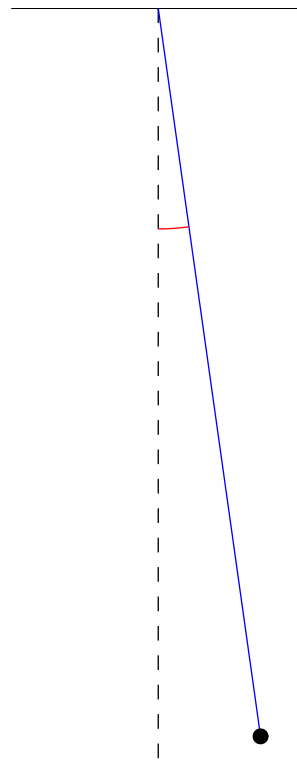
show damped.nb



(5) Simple pendulum:

$$\frac{d^2\theta}{dt^2} + \frac{g}{L} \sin \theta = 0 \quad (5)$$

- $\theta = \theta(t)$  is angle that arm makes with vertical
- $L$  is length of pendulum
- $g$  is gravitation constant



show pendulum.nb

(6) Airy's equation:

$$\frac{d^2y}{dx^2} + xy = 0 \quad (6)$$

related to theory of diffraction.

**Remark**  $\frac{d^2y}{dx^2} - xy = 0$  is also called Airy's equation.

show airy.nb

(7) Heat equation:

$$a^2 \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) = \frac{\partial w}{\partial t} \quad (7)$$

- $w = w(x, y, z, t)$  is temperature of a point  $(x, y, z)$  at time  $t$
- $a$  is a constant

show heat.nb



(8) Volterra's prey-predator equation:

$$\begin{cases} \frac{dx}{dt} = x(a - by) \\ \frac{dy}{dt} = -y(c - dx) \end{cases} \quad (8)$$

- $x = x(t)$  is prey population
- $y = y(t)$  predator population at time  $t$ .
- $a, b, c, d$  are positive constants

show prey-predator.nb

**Terminology** If unknown function is

- *function of a single variable*, the differential equation is called an *ordinary differential equation* (ODE)
- function of several variables, the differential equation is called a *partial differential equation* (PDE).

**Terminology** If unknown function is

- *function of a single variable*, the differential equation is called an *ordinary differential equation* (ODE)
- function of several variables, the differential equation is called a *partial differential equation* (PDE).

**Example**

- (1), (2), (3), (4), (5), (6), and (8) are ODE
- (7) PDE

**Terminology** If unknown function is

- *function of a single variable*, the differential equation is called an *ordinary differential equation* (ODE)
- function of several variables, the differential equation is called a *partial differential equation* (PDE).

**Example**

- (1), (2), (3), (4), (5), (6), and (8) are ODE
- (7) PDE

DE=ODE

**Definition** *Order* of a DE = order of *highest* derivative.

**Definition** *Order* of a DE = order of **highest** derivative.

## Example

- (1), (2) and (3) order 1

**Definition** *Order* of a DE = order of **highest** derivative.

### Example

- (1), (2) and (3) order 1
- (4), (5) and (6) order 2

**Definition** *Order* of a DE = order of **highest** derivative.

### Example

- (1), (2) and (3) order 1
- (4), (5) and (6) order 2
- (8) is a first order system.



## Terminology

- DE of order  $n$  can be written as (called *implicit* form)

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

where  $y'$  denotes  $\frac{dy}{dt}$  etc.

## Terminology

- DE of order  $n$  can be written as (called *implicit* form)

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

where  $y'$  denotes  $\frac{dy}{dt}$  etc.

- Usually, consider cases where  $y^{(n)}$  can be solved (*explicit* form)

$$y^{(n)} = f(t, y, y', y'', \dots, y^{(n-1)})$$

## Terminology

- DE of order  $n$  can be written as (called *implicit* form)

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

where  $y'$  denotes  $\frac{dy}{dt}$  etc.

- Usually, consider cases where  $y^{(n)}$  can be solved (*explicit* form)

$$y^{(n)} = f(t, y, y', y'', \dots, y^{(n-1)})$$

## Example

- |               |                   |               |
|---------------|-------------------|---------------|
| (1) 1st order | $F(t, y, y') = 0$ | implicit form |
|               | $y' = f(t, y)$    | explicit form |

## Terminology

- DE of order  $n$  can be written as (called *implicit* form)

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

where  $y'$  denotes  $\frac{dy}{dt}$  etc.

- Usually, consider cases where  $y^{(n)}$  can be solved (*explicit* form)

$$y^{(n)} = f(t, y, y', y'', \dots, y^{(n-1)})$$

## Example

(1) 1st order      $F(t, y, y') = 0$      implicit form

$y' = f(t, y)$      explicit form

(2) 2nd order      $F(t, y, y', y'') = 0$      implicit form

$y'' = f(t, y, y')$      explicit form

**Definition** DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

**Definition** DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

**Example**

(1) 1st order linear  $P(t)y' + Q(t)y = g(t)$

**Definition** DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

### Example

(1) 1st order linear  $P(t)y' + Q(t)y = g(t)$

The mapping  $y \mapsto P(t)y' + Q(t)y$  is linear.

**Definition** DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

### Example

(1) 1st order linear  $P(t)y' + Q(t)y = g(t)$

The mapping  $y \mapsto P(t)y' + Q(t)y$  is linear.

cf *Linear equation*  $Ax + By = C$

*The mapping from  $\mathbb{R}^2$  to  $\mathbb{R}$   $(x, y) \mapsto Ax + By$  is linear*



**Definition** DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

### Example

(1) 1st order linear  $P(t)y' + Q(t)y = g(t)$

The mapping  $y \mapsto P(t)y' + Q(t)y$  is linear.

cf *Linear equation*  $Ax + By = C$

*The mapping from  $\mathbb{R}^2$  to  $\mathbb{R}$   $(x, y) \mapsto Ax + By$  is linear*

(2) 2nd order linear  $P(t)y'' + Q(t)y' + R(t)y = g(t)$

**Definition** DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

### Example

(1) 1st order linear  $P(t)y' + Q(t)y = g(t)$

The mapping  $y \mapsto P(t)y' + Q(t)y$  is linear.

cf *Linear equation*  $Ax + By = C$

*The mapping from  $\mathbb{R}^2$  to  $\mathbb{R}$   $(x, y) \mapsto Ax + By$  is linear*

(2) 2nd order linear  $P(t)y'' + Q(t)y' + R(t)y = g(t)$

The mapping  $y \mapsto P(t)y'' + Q(t)y' + R(t)y$  is linear.

## Definition

- DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

- *Non-linear* = not linear.

## Definition

- DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

- *Non-linear* = not linear.

## Example

- $\diamond$  (1), (2), (4) and (6) are linear
  - $\diamond$  (3) and (5) non-linear.

## Definition

- DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

- ◊ ◦ If  $g(t) \equiv 0$ , it is called *homogeneous*,
  - otherwise, *non-homogeneous*.
- *Non-linear* = not linear.

## Example

- ◊ (1), (2), (4) and (6) are linear
  - ◊ (3) and (5) non-linear.

## Definition

- DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

- ◊ ◦ If  $g(t) \equiv 0$ , it is called *homogeneous*,
  - otherwise, *non-homogeneous*.
- *Non-linear* = not linear.

## Example

- ◊ (1), (2), (4) and (6) are linear
- ◊ (3) and (5) non-linear.
- ◊ (1), (4) and (6) are homogeneous
- ◊ (2) non-homogeneous.

## Definition

- DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

- ◇ ○ If  $g(t) \equiv 0$ , it is called *homogeneous*,
  - otherwise, *non-homogeneous*.
  - ◇ If all  $a_i(t)$  are constants, it is called *linear DE with constant coefficients*.
- *Non-linear* = not linear.

## Example

- ◇ (1), (2), (4) and (6) are linear
- ◇ (3) and (5) non-linear.
- ◇ (1), (4) and (6) are homogeneous
- ◇ (2) non-homogeneous.

## Definition

- DE of the following form is called *linear*.

$$a_n(t)y^{(n)} + a_{n-1}(t)y^{(n-1)} + \cdots + a_0(t)y = g(t)$$

- ◇ ○ If  $g(t) \equiv 0$ , it is called *homogeneous*,
  - otherwise, *non-homogeneous*.
  - ◇ If all  $a_i(t)$  are constants, it is called *linear DE with constant coefficients*.
- *Non-linear* = not linear.

## Example

- ◇ (1), (2), (4) and (6) are linear
- ◇ (3) and (5) non-linear.
- ◇ (1), (4) and (6) are homogeneous
- ◇ (2) non-homogeneous.
- (1), (2) and (4) have constant coefficients.



Usually, consider DE's for  $t$  belonging to an *interval*

Usually, consider DE's for  $t$  belonging to an *interval*

*Reason*

- $\frac{dy}{dt} = 0$  on an interval  $I \implies y$  is constant on  $I$ ;
- NOT TRUE if  $I$  is not an interval.

Usually, consider DE's for  $t$  belonging to an *interval*

*Reason*

- $\frac{dy}{dt} = 0$  on an interval  $I \implies y$  is constant on  $I$ ;
- NOT TRUE if  $I$  is not an interval.

**Definition** A *solution* to

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

in  $(a, b)$  is a function  $\varphi : (a, b) \longrightarrow \mathbb{R}$  such that

$$F(t, \varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t)) = 0 \quad \forall t \in (a, b)$$

Usually, consider DE's for  $t$  belonging to an *interval*

*Reason*

- $\frac{dy}{dt} = 0$  on an interval  $I \implies y$  is constant on  $I$ ;
- NOT TRUE if  $I$  is not an interval.

**Definition** A *solution* to

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

in  $(a, b)$  is a function  $\varphi : (a, b) \longrightarrow \mathbb{R}$  such that

$$F(t, \varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t)) = 0 \quad \forall t \in (a, b)$$

*Requirement*

- For all  $t \in (a, b)$ ,  $\varphi(t)$ ,  $\varphi'(t)$ ,  $\varphi''(t)$ ,  $\dots$ ,  $\varphi^{(n)}(t)$  exist.

Usually, consider DE's for  $t$  belonging to an *interval*

*Reason*

- $\frac{dy}{dt} = 0$  on an interval  $I \implies y$  is constant on  $I$ ;
- NOT TRUE if  $I$  is not an interval.

**Definition** A *solution* to

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

in  $(a, b)$  is a function  $\varphi : (a, b) \longrightarrow \mathbb{R}$  such that

$$F(t, \varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t)) = 0 \quad \forall t \in (a, b)$$

*Requirement*

- For all  $t \in (a, b)$ ,  $\varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t)$  exist.
- For all  $t \in (a, b)$ ,  $(t, \varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t))$  belongs to the domain of  $F$ .

Usually, consider DE's for  $t$  belonging to an *interval*

*Reason*

- $\frac{dy}{dt} = 0$  on an interval  $I \implies y$  is constant on  $I$ ;
- NOT TRUE if  $I$  is not an interval.

**Definition** A *solution* to

$$F(t, y, y', y'', \dots, y^{(n)}) = 0$$

in  $(a, b)$  is a function  $\varphi : (a, b) \longrightarrow \mathbb{R}$  such that

$$F(t, \varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t)) = 0 \quad \forall t \in (a, b)$$

*Requirement*

- For all  $t \in (a, b)$ ,  $\varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t)$  exist.
- For all  $t \in (a, b)$ ,  $(t, \varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t))$  belongs to the domain of  $F$ .
- For all  $t \in (a, b)$ ,  $F(t, \varphi(t), \varphi'(t), \varphi''(t), \dots, \varphi^{(n)}(t)) = 0$ .

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Terminology** A *solution* to a DE means a *solution* to the DE *in some open intervals*.



**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Terminology** A *solution* to a DE means a *solution* to the DE *in some open intervals*.

**Solution** For all  $t \neq 0$ ,  $\varphi'(t) + 2t\varphi(t)^2 = -2t^{-3} + 2t \cdot (t^{-2})^2$

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Terminology** A *solution* to a DE means a *solution* to the DE *in some open intervals*.

**Solution** For all  $t \neq 0$ ,

$$\begin{aligned}\varphi'(t) + 2t\varphi(t)^2 &= -2t^{-3} + 2t \cdot (t^{-2})^2 \\ &= -2t^{-3} + 2t^{-3}\end{aligned}$$

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Terminology** A *solution* to a DE means a *solution* to the DE *in some open intervals*.

**Solution** For all  $t \neq 0$ ,

$$\begin{aligned}\varphi'(t) + 2t\varphi(t)^2 &= -2t^{-3} + 2t \cdot (t^{-2})^2 \\ &= -2t^{-3} + 2t^{-3} \\ &= 0\end{aligned}$$

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Terminology** A *solution* to a DE means a *solution* to the DE *in some open intervals*.

**Solution** For all  $t \neq 0$ ,

$$\begin{aligned}\varphi'(t) + 2t\varphi(t)^2 &= -2t^{-3} + 2t \cdot (t^{-2})^2 \\ &= -2t^{-3} + 2t^{-3} \\ &= 0\end{aligned}$$

Thus  $\varphi$  is a solution to the DE in  $(0, \infty)$  and also in  $(-\infty, 0)$ .

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Terminology** A *solution* to a DE means a *solution* to the DE *in some open intervals*.

**Solution** For all  $t \neq 0$ ,

$$\begin{aligned} \varphi'(t) + 2t\varphi(t)^2 &= -2t^{-3} + 2t \cdot (t^{-2})^2 \\ &= -2t^{-3} + 2t^{-3} \\ &= 0 \end{aligned}$$

Thus  $\varphi$  is a solution to the DE in  $(0, \infty)$  and also in  $(-\infty, 0)$ .

**Remark** Can also say  $\varphi$  is a solution to the DE in  $(1, 5)$ .

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

Show that  $\varphi(t) = \frac{1}{t^2}$  is a solution.

**Terminology** A *solution* to a DE means a *solution* to the DE *in some open intervals*.

**Solution** For all  $t \neq 0$ ,

$$\begin{aligned} \varphi'(t) + 2t\varphi(t)^2 &= -2t^{-3} + 2t \cdot (t^{-2})^2 \\ &= -2t^{-3} + 2t^{-3} \\ &= 0 \end{aligned}$$

Thus  $\varphi$  is a solution to the DE in  $(0, \infty)$  and also in  $(-\infty, 0)$ .

**Remark** Can also say  $\varphi$  is a solution to the DE in  $(1, 5)$ .

**Remark** The interval  $(0, \infty)$  is maximal:

*If  $\varphi$  is a solution to the DE in an interval  $(a, b)$  and  $(a, b) \supset (0, \infty)$ , then  $(a, b) = (0, \infty)$ .*

**Definition** Let  $\varphi$  be a solution to a DE. An *interval of validity* of  $\varphi$  is an open interval  $(\alpha, \beta)$  such that

- $\varphi$  is a solution to the DE in  $(\alpha, \beta)$ ;
- if  $\varphi$  is a solution to the DE in  $(a, b)$  with  $(a, b) \supset (\alpha, \beta)$ , then  $(a, b) = (\alpha, \beta)$ .

**Definition** Let  $\varphi$  be a solution to a DE. An *interval of validity* of  $\varphi$  is an open interval  $(\alpha, \beta)$  such that

- $\varphi$  is a solution to the DE in  $(\alpha, \beta)$ ;
- if  $\varphi$  is a solution to the DE in  $(a, b)$  with  $(a, b) \supset (\alpha, \beta)$ , then  $(a, b) = (\alpha, \beta)$ .

### Remark

- A solution may have more than one (disjoint) intervals of validity.



**Definition** Let  $\varphi$  be a solution to a DE. An *interval of validity* of  $\varphi$  is an open interval  $(\alpha, \beta)$  such that

- $\varphi$  is a solution to the DE in  $(\alpha, \beta)$ ;
- if  $\varphi$  is a solution to the DE in  $(a, b)$  with  $(a, b) \supset (\alpha, \beta)$ , then  $(a, b) = (\alpha, \beta)$ .

### Remark

- A solution may have more than one (disjoint) intervals of validity.
- Different solutions may have different intervals of validity.

**Definition** Let  $\varphi$  be a solution to a DE. An *interval of validity* of  $\varphi$  is an open interval  $(\alpha, \beta)$  such that

- $\varphi$  is a solution to the DE in  $(\alpha, \beta)$ ;
- if  $\varphi$  is a solution to the DE in  $(a, b)$  with  $(a, b) \supset (\alpha, \beta)$ , then  $(a, b) = (\alpha, \beta)$ .

### Remark

- A solution may have more than one (disjoint) intervals of validity.
- Different solutions may have different intervals of validity.

To solve a DE means

- to find all solutions to the DE;
- if possible, for each solution, determine its interval(s) of validity.

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

- The following are solutions:
  - ◇  $\varphi(t) \equiv 0$
  - ◇  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

• The following are solutions:

◇  $\varphi(t) \equiv 0$

◇  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)

$$\begin{aligned}\varphi'_c(t) &= -(t^2 + c)^{-2} \cdot 2t \\ &= -2t[\varphi_c(t)]^2\end{aligned}$$

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

- The following are solutions:

- ◊  $\varphi(t) \equiv 0$

- ◊  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)

$$\begin{aligned}\varphi'_c(t) &= -(t^2 + c)^{-2} \cdot 2t \\ &= -2t[\varphi_c(t)]^2\end{aligned}$$

- No more solution (by E&U Thm).

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

- The following are solutions:

- ◊  $\varphi(t) \equiv 0$

- ◊  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)

$$\begin{aligned}\varphi'_c(t) &= -(t^2 + c)^{-2} \cdot 2t \\ &= -2t[\varphi_c(t)]^2\end{aligned}$$

- No more solution (by E&U Thm).
- Interval of Validity ?

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

- The following are solutions:

- ◇  $\varphi(t) \equiv 0$

- ◇  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)

$$\begin{aligned}\varphi'_c(t) &= -(t^2 + c)^{-2} \cdot 2t \\ &= -2t[\varphi_c(t)]^2\end{aligned}$$

- No more solution (*by E&U Thm*).
- Interval of Validity ?
  - ◇  $\varphi \equiv 0$  solution on  $\mathbb{R}$



**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

- The following are solutions:

- ◇  $\varphi(t) \equiv 0$

- ◇  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)

$$\begin{aligned}\varphi'_c(t) &= -(t^2 + c)^{-2} \cdot 2t \\ &= -2t[\varphi_c(t)]^2\end{aligned}$$

- No more solution (*by E&U Thm*).
- Interval of Validity ?
  - ◇  $\varphi \equiv 0$  solution on  $\mathbb{R}$
  - ◇  $\circ$  if  $c > 0$ ,  $\varphi_c$  solution on  $\mathbb{R}$

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

- The following are solutions:

- ◇  $\varphi(t) \equiv 0$

- ◇  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)

$$\begin{aligned}\varphi'_c(t) &= -(t^2 + c)^{-2} \cdot 2t \\ &= -2t[\varphi_c(t)]^2\end{aligned}$$

- No more solution (*by E&U Thm*).

- Interval of Validity ?

- ◇  $\varphi \equiv 0$  solution on  $\mathbb{R}$

- ◇ ○ if  $c > 0$ ,  $\varphi_c$  solution on  $\mathbb{R}$

- if  $c = 0$ ,  $\varphi_0$  solution on  $(-\infty, 0)$  and also on  $(0, \infty)$

**Example** Consider (1st order, non-linear) DE

$$y' + 2ty^2 = 0$$

- The following are solutions:

- ◇  $\varphi(t) \equiv 0$

- ◇  $\varphi_c(t) = (t^2 + c)^{-1}$  (where  $c$  is a constant)
 
$$\begin{aligned}\varphi'_c(t) &= -(t^2 + c)^{-2} \cdot 2t \\ &= -2t[\varphi_c(t)]^2\end{aligned}$$

- No more solution (by E&U Thm).

- Interval of Validity ?

- ◇  $\varphi \equiv 0$  solution on  $\mathbb{R}$

- ◇ ○ if  $c > 0$ ,  $\varphi_c$  solution on  $\mathbb{R}$

- if  $c = 0$ ,  $\varphi_0$  solution on  $(-\infty, 0)$  and also on  $(0, \infty)$

- if  $c = -p < 0$ ,  $\varphi_c$  solution on  $(-\infty, -\sqrt{p})$ ,  $(-\sqrt{p}, \sqrt{p})$  and  $(\sqrt{p}, \infty)$ .

$$\varphi_c(t) = \frac{1}{t^2 - p} \text{ is undefined at } \pm\sqrt{p}$$